OPTIMUM STRUCTURAL DESIGN, BEAM-COLUMNS

by

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ABSTRACT

OPTIMUM STRUCTURAL DESIGN

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The purpose of this thesis was to derive the equations for optimum design of slender beam-columns by analytical methods. Design charts for simply supported steel beam-columns have been constructed from the equations that were derived. Techniques which lead to fully stressed solutions were employed. The algebraic techniques which are tedious and difficult to handle are presented along with design charts and optimum design equations. From these equations and design charts, it is relatively easy to design a specific form of beam-column to optimum state without using trial and error techniques.

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LIST OF SYMBOLS

- A cross sectional area
- c effective column length ratio or distance from neutral axis to outter edge
- D tube diameter
- E modulus of elasticity
- e eccentricity
- FC, failure constraint
- h web depth
- I moment of inertia
- K, kp buckling coefficient
- k, ratio of flange thickness to web thickness
- L length
- M moment
- P concentrated load
- r radius of gyration
- s_A design stress
- \mathbf{s}_{E} Euler buckling stress
- SL local buckling stress
- s_v yield strength
- t thickness
- Ψ slack variable

BACKGROUND

Optimum structural design is the process of determining the best configuration (froms and proportions) over other possible choices which are acceptable under the applicable constraints (limitations & restrictions). Form is the shape and relative arrangements of the component elements while proportions are the size of components. (1)* Proportions are also called "design variables". (2)

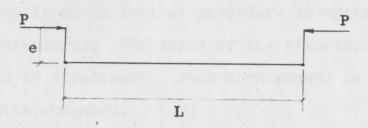
Leonard Spunt in Optimum Structural Design, (1) derived the optimum design process into five major steps as following:

Phase 1- Recognition of Environments

The loads acting on the structure and the purpose of the structure must be known since these limit the shape of the structure. For the beam-columns, the factors which are of environmental concern are:

- P, load on the structure
- e , essentricity of the load which causes moment on beam-column
- L , length of span
- c , factor which depends on end conditions

^{*}Numbers in parenthesis indicate reference cites.



$$\mathbf{E}_{\mathbf{S}} = \begin{cases} \mathbf{P} \\ \mathbf{L} \\ \mathbf{e} \\ \mathbf{c} \end{cases}$$

Fig. B.1

These factors are called environment factors (E_s) . Phase 2- Establishment of Criteria

The goal in optimizing such as minimum weight or minimum area is represented by a function. This funtion is called "merit function". (1) For example in designing a minimum cross section area of a circular tube column, the merit function is:

$$A = TDt \qquad -----*$$

where

A is cross section area

D is diameter of tube

t is thickness of wall

This function is also called "objective function". (2)

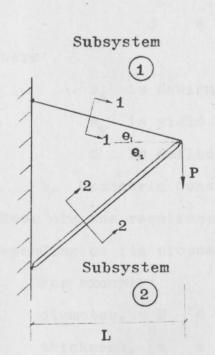
Phase 3- Specification of Form

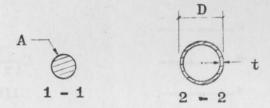
These is no analytical procedure to optimize the forms of the structures. The forms of the structure have to be predicted by experience. Each form should be optimized and the results compared.

When the form has been specified, the system variables are defined. There are three types of system variables:

- S_p proportion variables
- S₀ orientation variables
- S_ material variables

See Figure B.2





$$\begin{array}{c}
\text{(1)} \begin{cases} \text{Sp = A} \\ \text{Sm = E_1, syl} \end{cases}
\end{array}$$

$$2\begin{cases} S_p = D, t \\ S_m = E_2, S_{y2} \end{cases}$$

$$S_0 = \begin{cases} \theta_1 \\ \theta_2 \end{cases}$$

Fig. B.2

Phase 4- Recognition of Constraints

Since it is required to find the minimum area of a given section, the question is; what is the least area that can be used? The answer is; when it does not fail and it satisfies the geometric requirements. The constraints can be classified as two types.

a. Failure Constraints

These constraints are the limitations and restrictions that prevent the structure from excessive stressing and deflection and buckling.

For example:

$$s_A \leq s_y$$

$$s_A \leq \frac{nE}{(cL/r)^2}$$

$$d \leq 0.001L$$

Where

 s_{Δ} is design stress

 s_v is yield strength of material

d is deflection

b. Geometric Constraints

These are the requirements on the size of the structure depending on its proposed use.

For example:

Phase 5- Optimization

The techniques of optimization can be classified broadly as analytical and numerical.

Numerical Methods

These methods employ the concept of mathematical programming and the use of systematic numerical algorithms. The work that will be presented here employs only analytical methods.

Analytical Methods

An analytical methods employs algebraic techniques and the following:

a. Slack Variable

Slack variables are the parameters which are less than or equal to unity $(\psi \le 1)$. By employing slack variables, the failure constraints which are written in inequality forms can be changed to equality equations and the nature of inequality still remains.

For example:

where

$$s_A \leq s_y$$

$$s_A = \psi_y s_y$$

$$\psi_{y} \leq 1$$

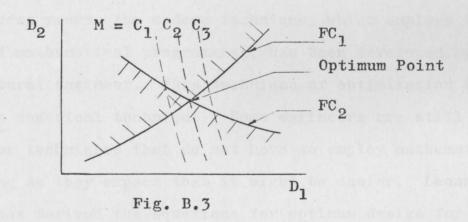
It will be seen that these two equations are the same.

be stated as follow:
failure modes which
neously under the action

ints cannot be explicitly
to the difficulty in
e to optimize by
technique.

Design Space

Design space is not a part of analytical methods, but it is a tool that assists in understanding the techniques used in optimization. The n-dimension space represents all possible design points, and the failure constraints can be visualized as a hypersurfaces which divide the design space into acceptable and unacceptable regions. Another type of hypersurface is the family of constant value contours of the merit function. (see Figure B.3)



The unacceptable regions are crosshatched in Figure B.3 and where

 D_1 , D_2 , are design variables.

FC, FC, are failure constraints.

M is a merit function, shown by dashed curves for each constant value.

INTRODUCTION

Most of the engineering structures today use trial and error procedure in their design project. Time saving economic designs have been a long desired goal. The best economical design that satisfies all the limitations without a lengthy trial process is desired by designers. This is the way that optimum design aspect arises. With the aid of the electrical computer, the problem of designing for an optimum state has become possible.

In recent years, the modern technique, which employs the concept of mathematical programming, has been developed by the structural engineer. This technique of optimization is called the numerical technique. Some engineers are still looking for techniques that do not have to employ mathematical programming as they expect that it might be easier. Leonard Spunt (1) has derived the equations for optimum design for beams and columns by using analytical methods. The background of this work has been taken from his book, "Optimum Structural Design" and extended to beam-columns.

The work that is presented here derives the equations that determine the best proportions for the specific form of beam-column. With these proportions, the beam-column will be the designed optimumly.

The shapes of the cross-sections of the beam-columns which will be considered in this study are as follows:

- 1. Thin Circular Tube
- 2. H Section
- 3. Thin Rectangular Tube

Only uniform cross sections will be considered.

CHAPTER I

CIRCULAR TUBE SECTION

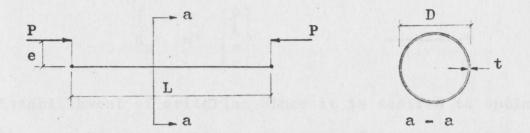


Fig. 1.1

For thin wall circular tube section shown in Figure 1.1;

A =
$$\pi Dt$$
 -----(1.1)
I = $\frac{\pi D^3 t}{8}$ -----(1.2)
 $r^2 = \frac{I}{A}$
= $\frac{D^2}{8}$ -----(1.3)
M = Pe -----(1.4)
 $s_A = \frac{Mc}{T} + \frac{P}{A}$
= $\frac{4Pe + DP}{\pi D^2 t}$ -----(1.5)

The phases of optimum design applied to the circular tube are as follows;

Recognition of environment; The following is applicable

$$\mathbf{E}_{\mathbf{S}} = \begin{cases} \mathbf{P} \\ \mathbf{L} \\ \mathbf{e} \\ \mathbf{c} \end{cases}$$

Establishment of criteria; Since it is desired to optimize the area of cross-section, the merit function is given by

$$A = \pi Dt$$

Specification of form; For the circular tube section considered here;

$$S_{p} = \begin{Bmatrix} D \\ t \end{Bmatrix} \qquad -----*$$

$$S_{m} = \begin{Bmatrix} E \\ s_{v} \end{Bmatrix} \qquad -----*$$

Recognition of constraints; Only failure constraints will be considered here. These constraints will prevent the structure from over stress and buckling.

 ${
m FC}_1$, design stress can not be more than yield strength;

$$s_A \leq s_y$$

 FC_2 , from Euler Buckling formula; $^{(1)}(4)$

$$s_{A} \leq \frac{\pi^{2}E}{(cL/r)^{2}}$$

$$\leq \frac{\pi^{2}ED^{2}}{8c^{2}L^{2}}$$

FC₃, local buckling;
$$(1)(4)$$

$$s_A \leq KE(t/D) \qquad -----*$$

where

FC; are failure constraints

c is factor which depends on end conditions

K is buckling coefficient

For optimization, the failure constraints are rewritten into equality equations by employing slack variables.

It is impossible to optimize the cross-section area directly because the difficulty in algebraic techniques.

Indirect method is presented here by optimizing the design stress.

By equating Equations (1.6) and (1.7);

By equating Equation (1.6) and (1.8);

$$\psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}} = \psi_{\mathbf{K}E}(\mathbf{t}/\mathbf{D})$$

$$\mathbf{t} = \frac{\psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}} \mathbf{D}}{\psi_{\mathbf{K}E}} ------(1.10)$$

Substituting the value of D from equation (1.9) into Equation (1.10);

t =
$$\frac{\Psi_{\mathbf{y}}^{\mathbf{s}}_{\mathbf{y}}}{\Psi_{\mathbf{L}}^{\mathbf{KE}}} \left(\frac{8\Psi_{\mathbf{y}}^{\mathbf{s}}_{\mathbf{y}}}{\Psi_{\mathbf{E}}^{\mathbf{E}}}\right)^{\frac{1}{2}} \stackrel{\mathbf{cL}}{=} --(1.11)$$

By equating Equations (1.6) and (1.5);

$$\Psi_{y}s_{y} = \frac{4Pe + DP}{\pi D^{2}t}$$
 ----(1.12)

Substituting the values of t and D from Equation (1.11) and (1.9) into Equation (1.12);

$$\psi_{y}s_{y} = \frac{4Pe + (\frac{8\psi_{y}s_{y}}{\psi_{E}E})^{\frac{1}{2}} \frac{cL}{\pi} P}{\frac{\pi 8\psi_{y}s_{y}c^{2}L^{2}}{\psi_{E}} \frac{\psi_{y}s_{y}}{\psi_{L}KE} (\frac{8\psi_{y}s_{y}}{\psi_{E}E})^{\frac{1}{2}} \frac{cL}{\pi}}$$

$$\psi_{y}^{7/2} = \frac{4Pe\psi_{E}^{3/2}\pi^{2}\psi_{L}KE^{5/2}}{8^{3/2}c^{3}L^{3}s^{7/2}} + \frac{\psi_{y}^{\frac{1}{2}}\pi\psi_{E}\psi_{L}E^{2}KP}{8s^{3}c^{2}L^{2}} (1.13)$$

Since there are two proportional variables, t and D, only two failure constraints can occur simultaneously. Letting FC_2 and FC_3 be the failure constraints that will occur simultaneously;

$$\Psi_{E} \& \Psi_{I} = 1$$
 -----(1.14)

Substituting the values of $\Psi_{\!E}$ and $\Psi_{\!L}$ from Equation (1.14) into Equation (1.13) and rearranging;

$$\psi_{y}^{7/2} - \frac{\psi_{y}^{\frac{1}{2}\pi E^{2}K(P/L)^{2}}}{8s_{y}^{3}c^{2}} - \frac{4(P/L^{2})(e/L)\pi^{2}KE^{5/2}}{8^{3/2}c^{3}s_{y}^{1/2}} = 0 -----(1.15)$$

For a simply supported beam-column;

$$c = 1$$

From Timoshenko; (4)

$$K = 0.4$$

Using AISI 1025 steel;

$$E = 30 \times 10^6 \text{ psi.}$$

 $s_v = 36,000 \text{ psi.}$

Substituting these values into Equation (1.15);

$$\psi_y^{7/2} - 3.04(P/L^2)\psi_y^{\frac{1}{2}} - 388(P/L^2)(e/L) = 0 ----(1.16)$$

Solutions of Equation (1.16) were obtained by running the computer programs (see Appendix A). For ψ_y = 1, the relation between P/L² and e/L wis shown in Figure 1.2 and Figure 1.3. The relation between ψ_y and P/L² for e/L equal to 0.00, 0.01, 0.05 and 0.10 are shown in Figure 1.4.

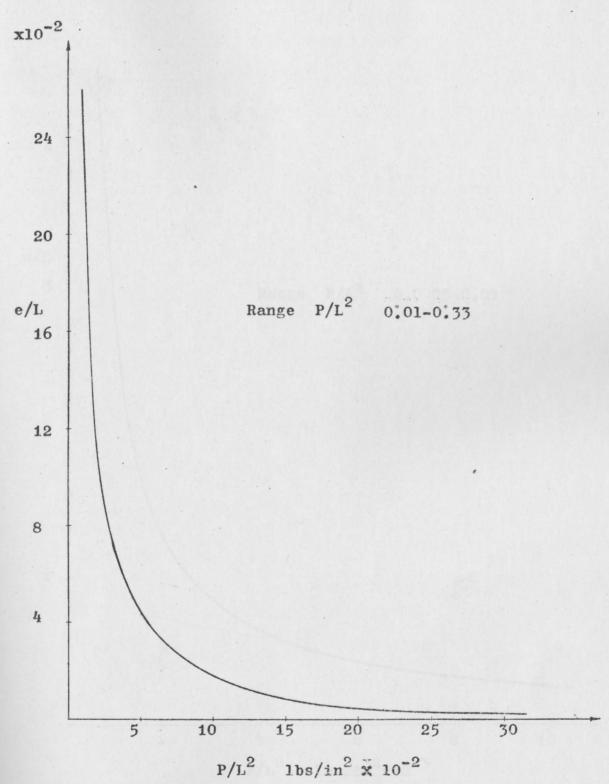


Figure 1.2 e/L & P/L² Relationship for $\psi_y = 1$

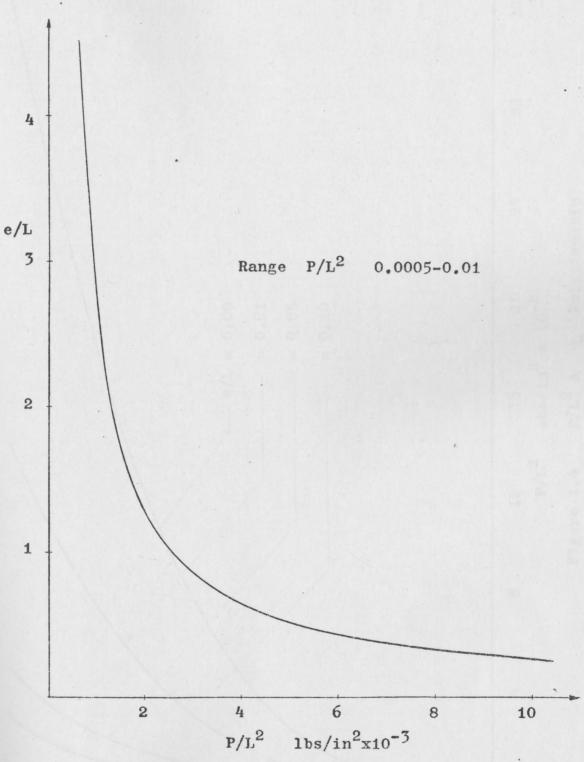
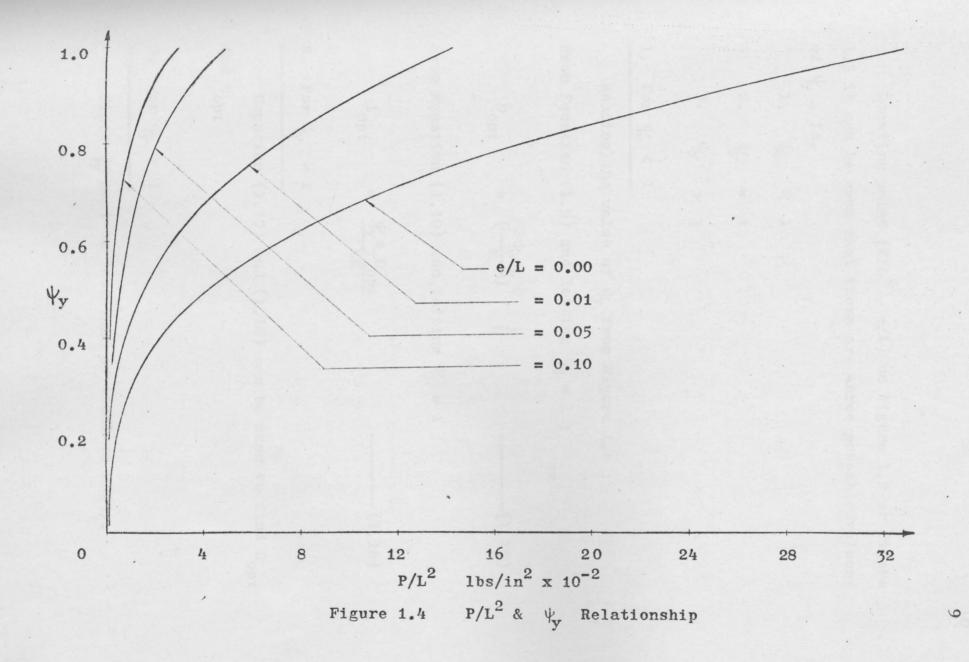


Figure 1.3 e/L & P/L² Relationship for $\psi_y = 1$



Locating point (P/L² , e/L) on Figure 1.2 or Figure 1.3 it can be seen that there are three possible values of ψ_y , ie,

1.
$$\psi_{y} < 1$$

$$2. \quad \psi_y = 1$$

3.
$$\Psi_y > 1$$

1. For $\psi_y < 1$

Reading the value of ψ_y from Figure 1.4;

From Equation (1.9) and letting $\Psi_E = 1$;

$$D_{\text{opt}} = \left(\frac{8\psi_y s_y}{E}\right)^{\frac{1}{2}} \frac{L}{\Pi} -----(1.17)$$

From Equation (1.10) and letting Ψ_L = 1;

$$t_{opt} = \frac{\Psi_{s}^{v} y^{D} opt}{KE} \qquad -----(1.18)$$

2. For $\psi_y = 1$

Equation (1.17) and (1.18) can be used to find $\mathbf{D}_{\mbox{\scriptsize opt}}$ and $\mathbf{t}_{\mbox{\scriptsize opt}}$

3. For $\psi_y > 1$

 $[\]sim$ Since ψ_y must be less than or equal to unity.

Letting
$$\Psi_{v} = 1$$
 -----*

Therefore, the values of Ψ_E and Ψ_L cannot be equal to unity at the same time because there are only two proportional variables (D & t).

Letting
$$\Psi_L = 1$$

Since $\psi_v = 1$, from Equation (1.6)

From Equation (1.8);

$$s_y = KE(t/D)$$
 -----(1.19)

From Equation (1.5);

$$s_y = \frac{4Pe + DP}{\pi D^2 t}$$
 -----(1.20)

Solving Equations (1.19) and (1.20) for $D_{\rm opt}$ and $t_{\rm opt}$. Result of these two equations were obtained by running the computer programs (see Appendix A) and shown in Figure 1.5 .

Note: In this case, if $\Psi_E = 1$, the optimum solution will not be obtained.

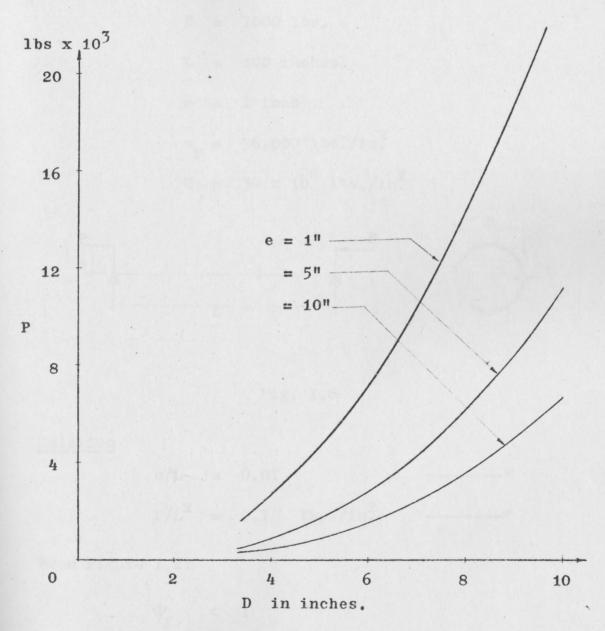


Figure 1.5 Result of Equations (1.19) & (1.20)

Example 1.1 Design a simply supported circular tube beamcolumn for the following environment factors and material variables:

P = 1000 lbs.

L = 100 inches

e = 1 inch

 $s_v = 36,000 \text{ lbs./in.}^2$

 $E = 30 \times 10^6$ lbs./in².

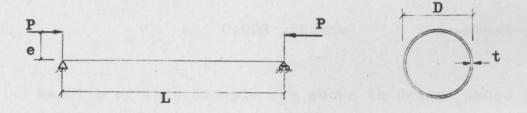


Fig. 1.6

Solution

$$e/L = 0.01$$
 ----*
 $P/L^2 = 0.1$ lbs./in² ----*

From Figure 1.2;

$$\Psi_y$$
 < 1

From Figure 1.4;

$$\Psi_{y} = 0.892$$

From Equation (1.17);

$$D_{\text{opt}} = \left(\frac{8 \times 0.892 \times 36,000}{30 \times 10^6}\right)^{\frac{1}{2}} \frac{100}{3.14}$$

$$= 2.95 \text{ inches}$$

From Equation (1.18);

$$t_{opt} = \frac{0.892 \times 36,000}{0.4 \times 30 \times 10^6} \times 2.95$$

$$= 0.008 \text{ inches}$$

Results of this example are shown in design space in Figure 1.7 .

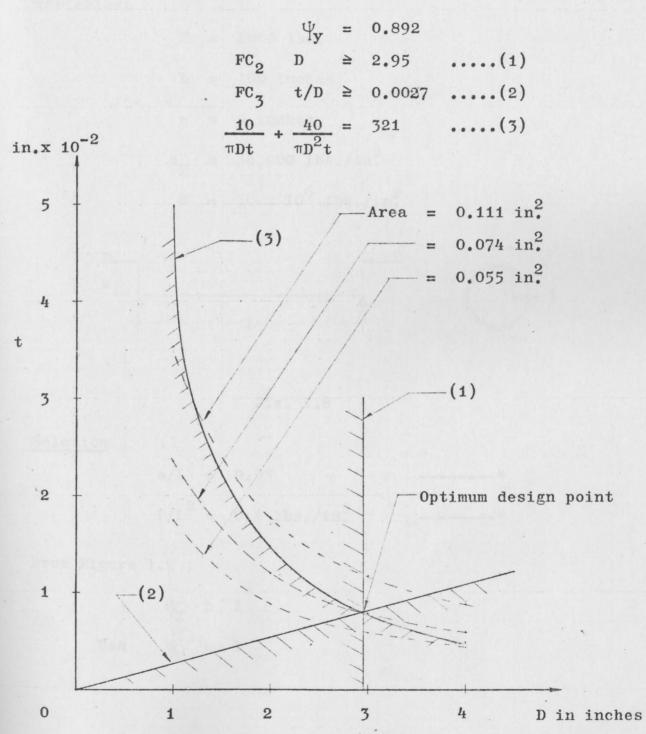


Figure 1.7 Design space of Example 1.1, unacceptable regions are shown crosshatched.

Example 1.2 Design a simply supported circular beamcolumn for the following environment factors and material variables:

P = 1000 lbs.

L = 100 inches

e = 5 inches

 $s_y = 36,000 \text{ lbs./in.}^2$

 $E = 30 \times 10^6 \text{ lbs./in.}^2$

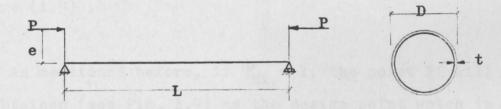


Fig. 1.8

Solution

$$e/L = 0.05$$
 -----*
 $P/L^2 = 0.1 \text{ lbs./in.}^2$ -----*

From Figure 1.2;

$$\Psi_y > 1$$

Use $\Psi_y = 1$

From Figure 1.5;

From Equation (1.19);

Results of this example are shown in design space in Figure (1.9) .

As mentioned before, if $\Psi_{\rm Ex}$ = 1, the point P' will be obtained (see Fig. 1.9) as the design point which is not the optimum design point.

The contraints that intersect at the optimum design point are called "active constraints". The other constraints are called "passive constraints".

In Fig. 1.9 FC $_3$ is an active constraint and FC $_2$ is a passive constraint. FC $_1$ is also an active constraint since ψ_y = 1 .

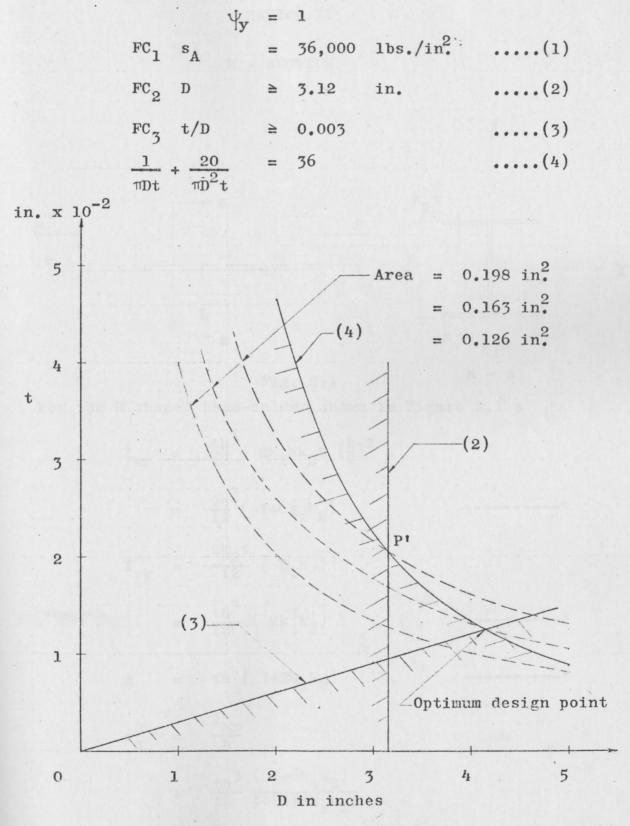
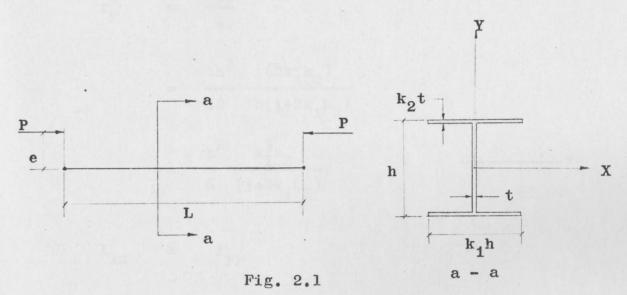


Figure 1.9 Design space of Example 1.2, unacceptable regions are shown crosshatched.

CHAPTER II

H - SECTION



For the H shaped beam-column shown in Figure 2.1;

$$I_{xx} = \frac{\tanh^{3}}{12} + 2k_{1}hk_{2}t \left(\frac{h}{2}\right)^{2}$$

$$= \frac{\tanh^{3}}{12} \left(1 + 6k_{1}k_{2}\right) ------*$$

$$I_{yy} = \frac{2k_{2}t}{12} \left(k_{1}h\right)^{3}$$

$$= \frac{th^{3}}{12} \left(2k_{1}^{3}k_{2}\right) ------*$$

$$A = th \left(1 + 2k_{1}k_{2}\right) ------*$$

$$r_{x}^{2} = \frac{I_{xx}}{A}$$

$$= \frac{th^{3}}{12} \frac{\left(1 + 6k_{1}k_{2}\right)}{th\left(1 + 2k_{1}k_{2}\right)}$$

The failure constraints applied to the H-section shown in Figure 2.1 as follows:

FC₁, local bucking in flange; (1)(4)

s_A
$$\leq$$
 s_{Lf}

$$\leq$$
 0.385 E $(\frac{k_2 t}{k_1 h/2})^2$

$$= \Psi_{Lf}$$
 0.385 E $(\frac{k_2 t}{k_1 h/2})^2$ ----(2.1)

where

 s_A is design stress

 $s_{\text{I.f}}$ is local buckling failure stress in flange

 $\mathbf{k_1},~\mathbf{k_2},~\mathbf{t}$ and h are proportional variables shown in

Figure 2.1

YII is slack variable

FC₂, local buckling in web; (4)(5)

$$s_{A} \leq s_{Lw}$$

$$\leq k_{p} E (t/h)^{2}$$

$$= \psi_{Lw} k_{p} E (t/h)^{2} -----(2.2)$$

where

 \mathbf{s}_{Lw} is local buckling failure stress in web \mathbf{k}_{p} is buckling coefficient

FC₃, Euler buckling in bending axis; (1)(4)

$$s_{A} \leq s_{EX}$$

$$\leq \frac{\pi^{2}E}{c^{2}L^{2}} \frac{h^{2}}{12} \frac{(1+6k_{1}k_{2})}{(1+2k_{1}k_{2})}$$

$$= \Psi_{EX} \frac{\pi^{2}E}{c^{2}L^{2}} \frac{h^{2}}{12} \frac{(1+6k_{1}k_{2})}{(1+2k_{1}k_{2})} - - - - - - - - (2.3)$$

where

 \mathbf{s}_{Ex} is buckling stress in bending axis

c is factor which depends on end conditions

FC4, Euler buckling in lateral direction; (1)(4)

$$s_{A1} \leq s_{Ey}$$

$$\leq \frac{\pi^2 E}{c^2 L^2} \frac{h^2}{6} \frac{k_1^3 k_2}{(1+2k_1 k_2)} \qquad -----(2.4)$$

where

 \mathbf{s}_{A1} is compressive stress due to axial load only \mathbf{s}_{Ey} is buckling stress in lateral direction

FC5, design stress can not be more than yield strength;

$$s_A \leq s_y$$

$$= \psi_y s_y$$
-----(2.5)

For linear materials in which the applied stress is not more than yield strength. The formula for combined axial and bending stress is;

$$s_{A} = \frac{P}{A} + \frac{M.c}{I_{xx}}$$

$$= \frac{P}{th(1+2k_{1}k_{2})} + \frac{6 Pe}{th^{2}(1+6k_{1}k_{2})} ----(2.6)$$

Using the same procedure used in Chapter I, the method proceeds indirectly by optimizing the design stress.

By equating Equations (2.1) and (2.2);

$$\Psi_{Lw}^{k}_{p} E(t/h)^{2} = \Psi_{Lf} 0.358 E \left(\frac{k_{2}t}{k_{1}h/2}\right)^{2}$$

Letting $\Psi_{Lw} = \Psi_{Lf}$ by S.M.D.

$$k_2 = k_1 \left(\frac{k_p}{1.54}\right)^{\frac{1}{2}}$$
 ----(2.7)

By equating Equations(2.5) and (2.6);

$$\psi_{y}s_{y} = \frac{P}{\text{th}(1+2k_{1}k_{2})} + \frac{6Pe}{\text{th}^{2}(1+6k_{1}k_{2})} -----(2.8)$$

Multiplying Equation (2.2) by Equation (2.3);

$$s_A^2 = \Psi_{Lw} k_p E (t/h)^2 \Psi_{EX} \frac{\pi^2 E}{c^2 L^2} \frac{h^2}{12} \frac{(1+6k_1k_2)}{(1+2k_1k_2)} --(2.9)$$

Substituting the value of s_A from Equation (2.5) into Equation (2.9);

$$\psi_{y}^{2} s_{y}^{2} = \psi_{Lw} \psi_{Ex} k_{p} \frac{t^{2} \pi^{2} E^{2}}{12 e^{2} L^{2}} \frac{(1+6k_{1}k_{2})}{(1+2k_{1}k_{2})}$$

$$t^{2} = \frac{12 e^{2} L^{2} \psi_{y}^{2} s_{y}^{2}}{\psi_{Lw} \psi_{Ex} k_{p} \pi^{2} E^{2}} \frac{(1+2k_{1}k_{2})}{(1+6k_{1}k_{2})}$$

t =
$$\frac{12^{\frac{1}{2}} \text{cL} \psi_y s_y}{(\psi_{LW} \psi_{EX}^{-\frac{1}{2}})^{\frac{1}{2}} k_p^{\frac{1}{2}} \pi E}$$
 $\frac{(1+2k_1 k_2)^{\frac{1}{2}}}{(1+6k_1 k_2)^{\frac{1}{2}}}$ ----(2.10)

By equating Equations (2.3) and (2.5);

$$\Psi_{y}s_{y} = \Psi_{Ex} \frac{\pi^{2}E}{e^{2}L^{2}} \frac{h^{2}}{12} \frac{(1+6k_{1}k_{2})}{(1+2k_{1}k_{2})}$$

$$h = \frac{\Psi_{y}^{\frac{1}{2}}s_{y}^{\frac{1}{2}}12^{\frac{1}{2}}cL}{\Psi_{Ex}^{\frac{1}{2}}\pi E^{\frac{1}{2}}} \frac{(1+2k_{1}k_{2})^{\frac{1}{2}}}{(1+6k_{1}k_{2})^{\frac{1}{2}}} -----(2.11)$$

Substituting the values of t and h from Equations (2.10) and (2.11) into Equation (2.8);

$$\Psi_{y}^{s}_{y} = \frac{P}{12^{\frac{1}{2}}cL\psi_{y}s_{y}} \frac{(1+2k_{1}k_{2})^{\frac{1}{2}}\psi_{y}^{\frac{1}{2}}s_{y}^{\frac{1}{2}}12^{\frac{1}{2}}cL}{(\psi_{Lw}\psi_{Ex})^{\frac{1}{2}}k_{p}^{\frac{1}{2}}\pi E} \frac{(1+2k_{1}k_{2})^{\frac{1}{2}}\psi_{y}^{\frac{1}{2}}s_{y}^{\frac{1}{2}}12^{\frac{1}{2}}cL}{(1+6k_{1}k_{2})^{\frac{1}{2}}}\frac{(1+2k_{1}k_{2})^{\frac{1}{2}}}{(1+6k_{1}k_{2})^{\frac{1}{2}}}(1+2k_{1}k_{2})}$$

$$\begin{array}{c} + \frac{12^{\frac{1}{2}} \text{cL} \, \psi_{y} \text{s}_{y}}{(\psi_{Lw} \, \psi_{Ex})^{\frac{1}{2}} \text{k}_{p}^{\frac{1}{2}} \text{TE}} & \frac{(1 + 2 \text{k}_{1} \text{k}_{2})^{\frac{1}{2}} \, \psi_{y} \text{s}_{y}}{(1 + 6 \text{k}_{1} \text{k}_{2})^{\frac{1}{2}}} & \frac{(1 + 2 \text{k}_{1} \text{k}_{2})}{(1 + 6 \text{k}_{1} \text{k}_{2})} & (\text{L} + 6 \text{k}_{1} \text{k}_{2}) \end{array}$$

Simplifying the above equation and letting $\Psi_{Lw}=\Psi_{Ex}=1$ and for the simple support end condition, c=1. Thus;

$$\frac{P}{L^{2}} = \frac{12^{3/2} \psi_{y}^{3} s_{y}^{3} (1 + 2k_{1}k_{2})^{2}}{k_{p}^{\frac{1}{2}} \left[\pi^{2} E^{3/2} (1 + 6k_{1}k_{2}) 12^{\frac{1}{2}} \psi_{y}^{\frac{1}{2}} s_{y}^{\frac{1}{2}} + 6 \frac{e}{L} \pi^{3} E^{2} (1 + 6k_{1}k_{2})^{\frac{1}{2}} (1 + 2k_{1}k_{2})^{\frac{1}{2}} \right]}$$

From Equation (2.12) and letting ψ_v = 1;

$$\frac{P}{L^{2}} = \frac{12^{3/2} s_{y}^{3} (1+2k_{1}k_{2})^{2}}{k_{p}^{\frac{1}{2}} \left[\pi^{2}E^{3/2}(1+6k_{1}k_{2})12^{\frac{1}{2}}s_{y}^{\frac{1}{2}}+6\frac{e}{L} \pi^{3}E^{2} (1+6k_{1}k_{2})^{\frac{1}{2}}(1+2k_{1}k_{2})^{\frac{1}{2}}\right]}$$
-----(2.13)

From BUCKLING STRENGTH of METAL STRUCTURES by Bleich: (5)

From Equation (2.7);

$$k_2 = k_1 (k_p/1.54)^{\frac{1}{2}}$$
 ----*

 $e/L = 0.00,$ $k_2 = 1.53 k_1$
 $e/L = 0.01,$ $k_2 = 1.89 k_1$
 $e/L = 0.05,$ $k_2 = 2.22 k_1$
 $e/L = 0.10,$ $k_2 = 2.59 k_1$
 $e/L > 0.10,$ $k_2 = 3.76 k_1$

Using AISI 1025 steel;

$$E = 30 \times 10^6 \text{ psi.}$$

 $s_y = 36,000 \text{ psi.}$

Substituting the above values into Equation (2.13), the relation between P/L^2 and k_1 are shown in Figures 2.2 - 2.6 for each value of e/L. (see computer program in Appendix A)

The next step is to check whether FC_4 is satisfied or not. From Equation (2.4);

$$s_{A1} \leq \frac{\pi^{2}E}{e^{2}L^{2}} \frac{h^{2}}{6} \frac{k_{1}^{3}k_{2}}{(1+2k_{1}k_{2})}$$

$$\frac{P}{th(1+2k_{1}k_{2})} = \Psi_{Ey} \frac{\pi^{2}E}{e^{2}L^{2}} \frac{h^{2}}{6} \frac{k_{1}^{3}k_{2}}{(1+2k_{1}k_{2})}$$

$$P = \Psi_{Ey} \frac{\pi^{2}E}{e^{2}L^{2}} \frac{th^{3}}{6} k_{1}^{3}k_{2} -----(2.14)$$

Substituting the values of t and h from Equations (2.10) and (2.11) into Equation (2.14) and simplifying:

$$\frac{P}{L^{2}} = \frac{24 \Psi_{Ey} e^{2} \Psi_{y}^{5/2} s_{y}^{5/2}}{\Psi_{Lw}^{\frac{1}{2}} \Psi_{Ex}^{2} k_{p}^{\frac{1}{2}} \Pi^{2} E^{3/2}} \frac{(1+2k_{1}k_{2})^{2} k_{1}^{3} k_{2}}{(1+6k_{1}k_{2})^{2}} ---(2.15)$$

From Equation (2.15) and letting $\psi_{Lw} = \psi_{Ex} = \psi_{Ey} = 1$ and for the simple support end condition, c = 1. Thus;

$$\frac{P}{L^2} = \frac{2^4 \psi_y^{5/2} s_y^{5/2}}{k_p^{\frac{1}{2}} \pi^2 E^{3/2}} \frac{(1+2k_1k_2)^2}{(1+6k_1k_2)^2} k_1^3 k_2 -----(2.16)$$

From Equation (2.16) and with ψ_y = 1;

$$\frac{P}{L^{2}} = \frac{24 \text{ s}_{y}^{5/2}}{\text{k}_{p}^{\frac{1}{2}\pi^{2}E^{3/2}}} = \frac{(1+2\text{k}_{1}\text{k}_{2})^{2}}{(1+6\text{k}_{1}\text{k}_{2})^{2}} \text{ k}_{1}^{3}\text{k}_{2} -----(2.17)$$

Equation (2.17) is satisfied for FC_1 , FC_2 , FC_3 , FC_4 , and FC_5 , but it is not satisfied for Equation (2.8). The relation between P/L^2 and k_1 of Equation (2.17) are shown in Figures 2.2 - 2.6. The computer program is shown in Appendix A.

Since
$$I_{xx} \geq I_{yy}$$

 $1 + 6k_1k_2 \geq 2k_1^3k_2$ ----*

For e/L = 0.00; $1 + 9.18k_1^2 \ge 3.06k_1^4$ k₁ ≤ 1.77 For e/L = 0.01; $1 + 11.34k_1^2 \ge 3.72k_1^4$ k₁ ≤ 1.74 -----* For e/L = 0.05; $1 + 13.32k_1^2 \ge 4.44k_1^4$ k₁ \(\) 1.74 For e/L = 0.10; $1 + 15.54k_1^2 \ge 5.18k_1^4$ k₁ ≤ 1.74 ----* For e/L = 0.20; $1 + 22.56k_1^2 \ge 7.52k_1^4$ k₁ ≤ 1.74 ----*

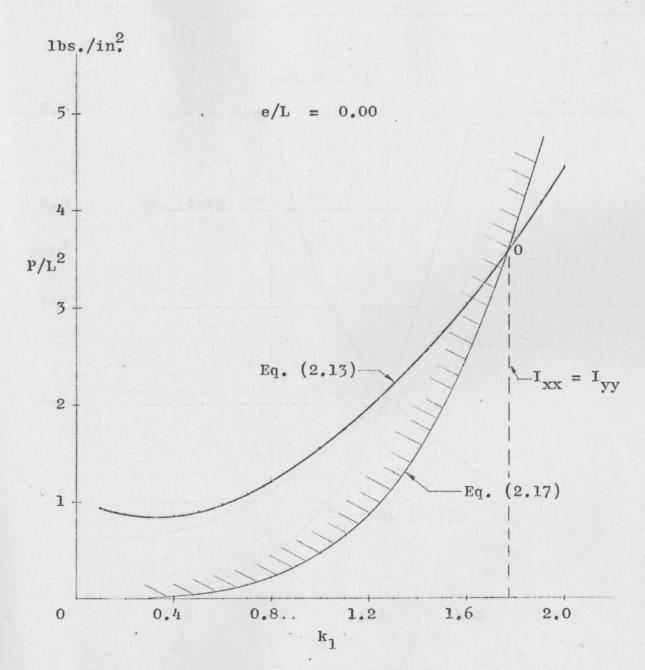


Fig. 2.2 Point 0 is the only design point when $s_A = s_y$, region which violates FC_4 is shown by crosshatching.

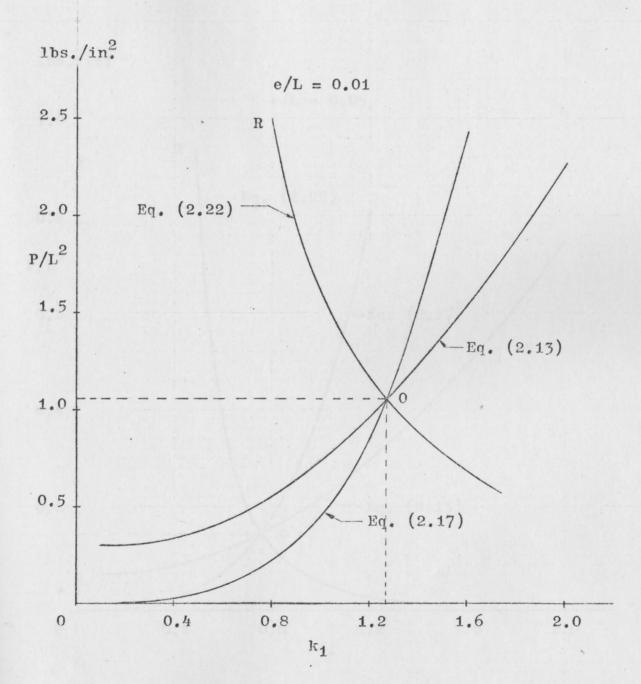


Fig. 2.3 Curve OR is design curve when $s_A = s_y$.

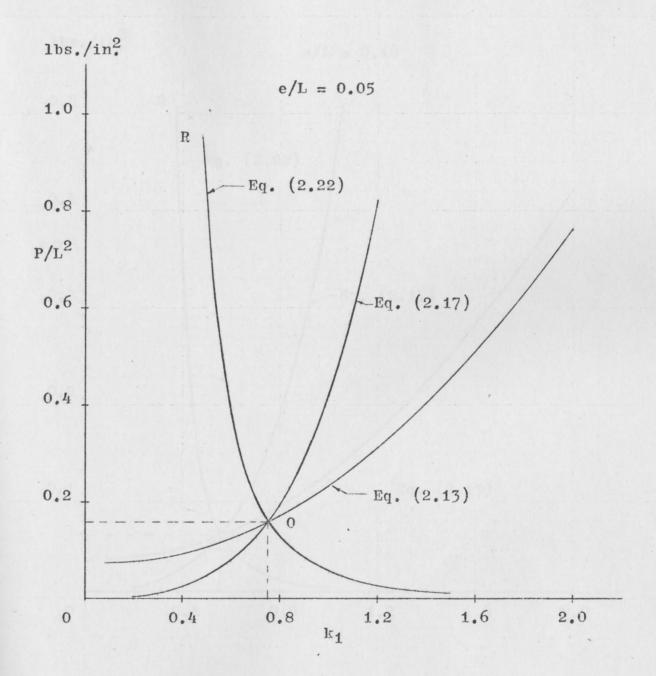


Fig. 2.4 Curve OR is design curve when $s_A = s_y$.

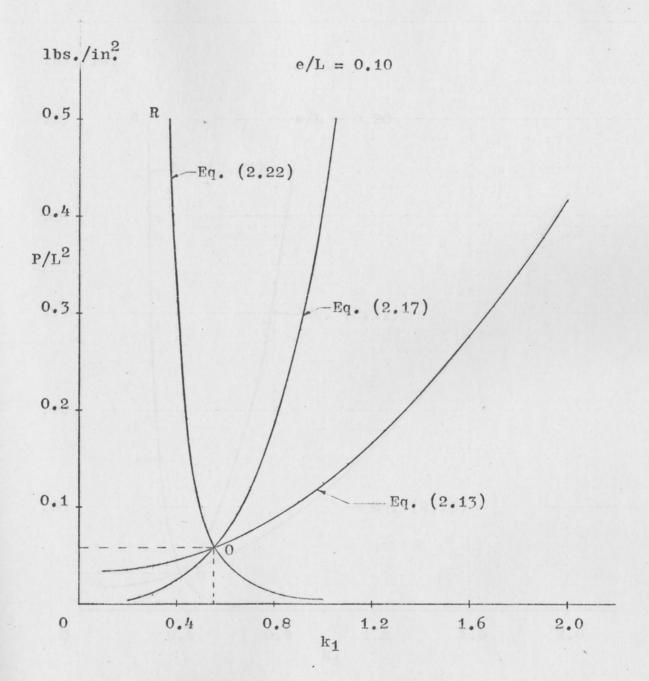


Fig. 2.5 Curve OR is design curve when $s_A = s_y$.

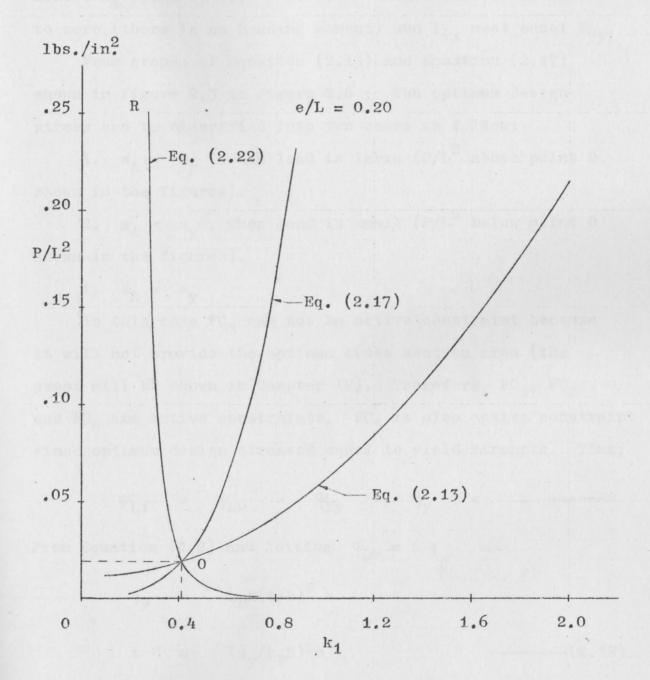


Fig. 2.6 Curve OR is design curve when $s_A = s_y$.

In Figure 2.2 , point 0 is the only design point and hence, $\mathbf{k_1}$ equal to 1.77 , because in this case, e is equal to zero (there is no bending moment) and $\mathbf{I_{xx}}$ must equal $\mathbf{I_{yy}}$.

From graphs of Equation (2.13) and Equation (2.17) shown in Figure 2.3 to Figure 2.6; The optimum design stress can be classified into two cases as follow:

- 1. $s_A = s_y$, when load is large $(P/L^2$ above point 0 shown in the figures).
- 2. $s_A < s_y$, when load is small $(P/L^2 \text{ below point 0})$ shown in the figures).

1.
$$s_A = s_y$$

In this case FC_3 can not be active constraint because it will not provide the optimum cross section area (the proof will be shown in Chapter IV). Therefore, FC_1 , FC_2 and FC_4 are active constraints. FC_5 is also active constraint since optimum design stressed equal to yield strength. Thus;

$$\psi_{Lf} = \psi_{Lw} = \psi_{Ey} = \psi_y = 1 ----*$$
 From Equation (2.2) and letting $\psi_{Lw} = 1$;

$$s_y = k_p E(t/h)^2$$

 $t = (s_y/k_p E)^{\frac{1}{2}}h$ -----(2.18)

From Equation (2.14) and letting $\Psi_{\rm Ey}$ = 1 and for simple support end condition, c = 1 . Thus;

$$P = \frac{\pi^2 E}{L^2} \frac{th^3}{6} k_1^3 k_2 \qquad -----(2.19)$$

Substituting value of t from Equation (2.18) into Equation (2.19) and rearranging;

$$h^{4} = \frac{6PL^{2}k^{\frac{1}{2}}_{p}}{\pi^{2}s^{\frac{1}{2}}E^{\frac{1}{2}}k^{\frac{7}{3}}k_{2}}$$

$$h = \left(\frac{6PL^{2}k^{\frac{1}{2}}_{p}}{\pi^{2}s^{\frac{1}{2}}E^{\frac{1}{2}}k^{\frac{7}{3}}k_{2}}\right)^{\frac{1}{2}} -----(2.20)$$

Substituting value of h from Equation (2.20) into Equation

(2.18);

$$t = (s_y/k_pE)^{\frac{1}{2}} \left(\frac{6PL^2k_p^{\frac{1}{2}}}{\pi^2 s_y^{\frac{1}{2}E^{\frac{1}{2}}k_1^{\frac{1}{2}}k_2}}\right)^{\frac{1}{4}} -----(2.21)$$

Substituting values of t and h from Equations (2.20) and (2.21) into Equation (2.6) and simplifying;

$$\mathbf{s_y} = \frac{(P/L^2)^{\frac{1}{2}} k_P^{\frac{1}{4}} E^{3/4} \pi k_1^{3/2} k_2^{\frac{1}{2}}}{6^{\frac{1}{2}} \mathbf{s_y^{\frac{1}{4}}} (1 + 2k_1 k_2)} + \frac{6^{\frac{1}{4}} (P/L^2)^{\frac{1}{4}} (e/L) k_P^{1/8} E^{7/8} \pi^{3/2} k_1^{9/4} k_2^{3/4}}{\mathbf{s_y^{1/8}} (1 + 6k_1 k_2)} - - - - (2.22)$$

The relation between P/L^2 and k_1 in Equation (2.22) was obtained by writing a computer program and are shown in Figure 2.3 to Figure 2.6. For designing, the relation between P/L^2 and k_1 of Equation (2.22) is plotted in more accurate scale shown in Figure 2.7 to Figure 2.10.

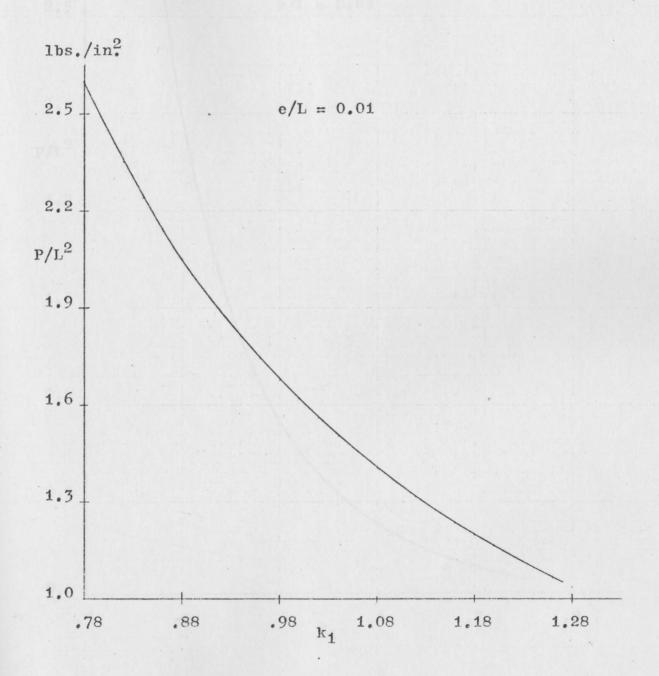


Fig. 2.7 Relation between P/L² and k_1 in Equation (2.22) when $s_A = s_y$.

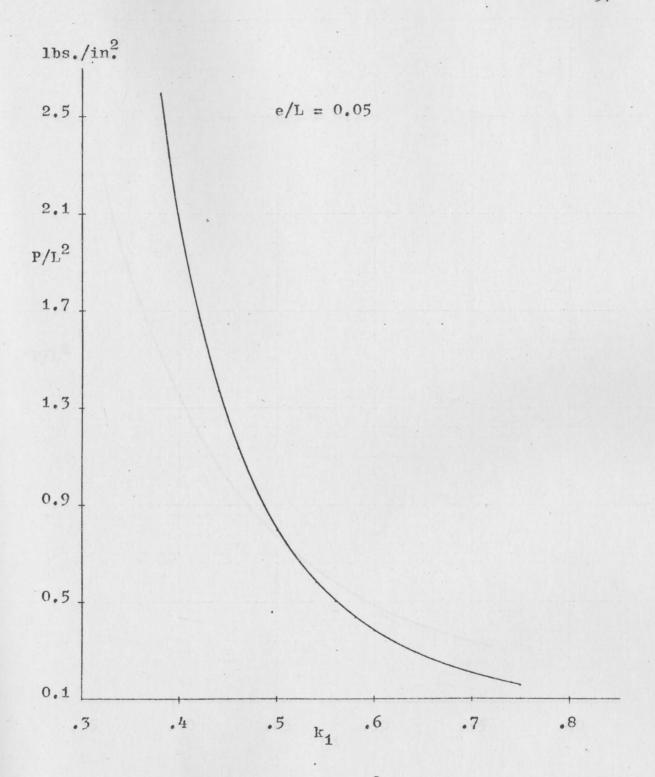


Fig. 2.8 Relation between P/L^2 and k_1 in Equation (2.22) when $s_A = s_y$.

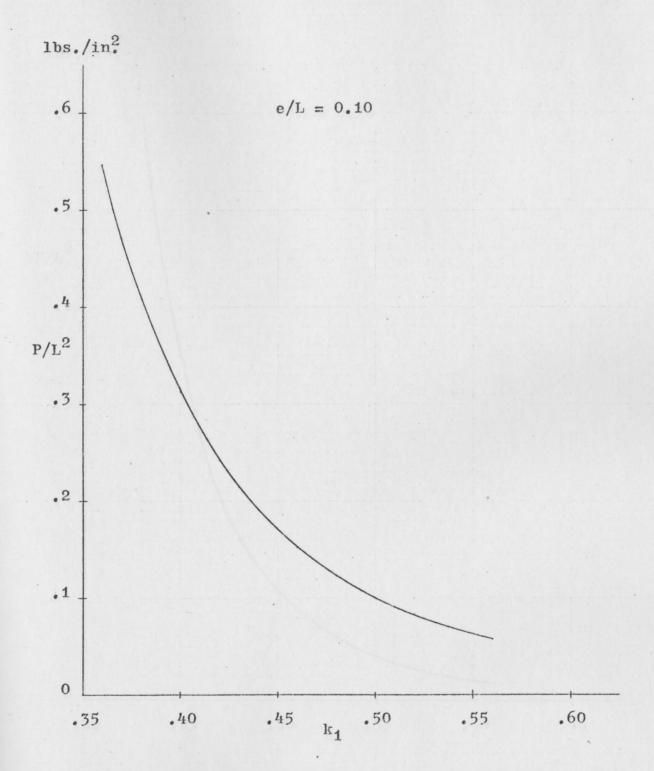


Fig. 2.9 Relation between P/L^2 and k_1 in Equation (2.22) when $s_A = s_y$.

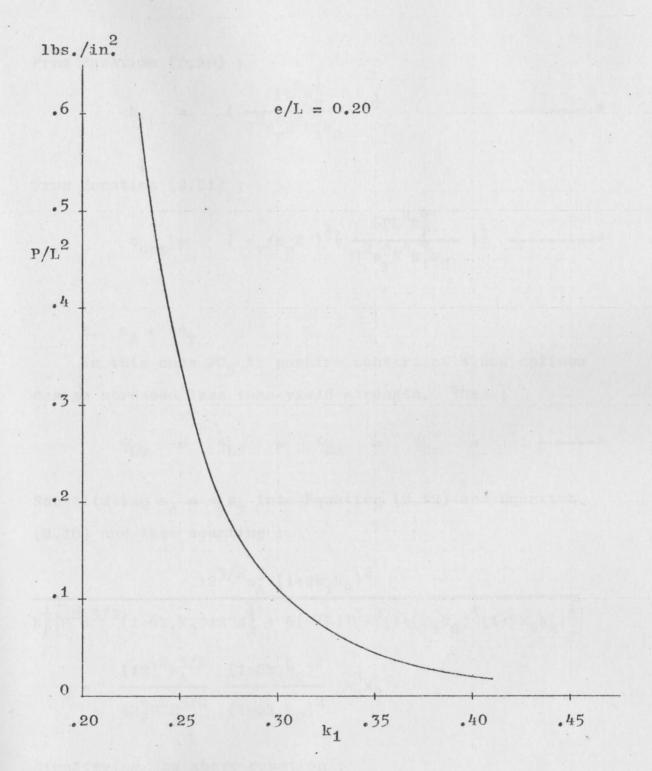


Fig. 2.10 Relation between P/L^2 and k_1 in Equation (2.22) when $s_A = s_y$.

From Equation (2.20);

$$h_{\text{opt}} = \left(\frac{6PL^2k_{\text{p}}^{\frac{1}{2}}}{\pi^2s_{\text{y}}^{\frac{1}{2}}E^{\frac{1}{2}}k_{1}^{3}k_{2}}\right)^{\frac{1}{4}}$$
 -----*

From Equation (2.21);

$$t_{opt} = (s_y/k_p E)^{\frac{1}{2}} (\frac{6PL^2k_p^{\frac{1}{2}}}{\pi^2 s_y^{\frac{1}{2}E^{\frac{1}{2}}k_1^{\frac{1}{2}}k_2}})^{\frac{1}{4}}$$
 ----*

In this case FC_5 is passive constraint since optimum design stressed less than yield strength. Thus;

$$\Psi_{Lw} = \Psi_{Lf} = \Psi_{Ex} = \Psi_{Ey} = 1 -----*$$

Substituting $s_A = \psi_y s_y$ into Equation (2.12) and Equation (2.16) and then equating ;

$$\frac{12^{3/2} s_A^3 (1+2k_1 k_2)^2}{k_P^{\frac{1}{2}} \left[\pi^2 E^{3/2} (1+6k_1 k_2) 12^{\frac{1}{2}} s_A^{\frac{1}{2}} + 6(e/L) \pi^3 E^2 (1+6k_1 k_2)^{\frac{1}{2}} (1+2k_1 k_2)^{\frac{1}{2}} \right]}$$

$$= \frac{(12)^2 s_A^{5/2}}{6k_P^{\frac{1}{2}} \pi^2 E^{3/2}} \frac{(1+2k_1 k_2)^2}{(1+6k_1 k_2)^2} k_1^3 k_2$$

Simplifying the above equation;

$$s_{A} = \left[\frac{12^{\frac{1}{2}}k_{1}k_{2}(e/L) \pi E^{\frac{1}{2}} (1+2k_{1}k_{2})^{\frac{1}{2}}}{(1+6k_{1}k_{2})^{\frac{3}{2}-2k_{1}^{3}k_{2}(1+6k_{1}k_{2})^{\frac{1}{2}}}\right]^{2} -----(2.23)$$

The relation between s_A and k_1 in Equation (2.23) is shown in Figure 2.11 . Substituting the values of s_A and k_1 from Equation (2.23) into Equation (2.12), or Equation (2.16), can yield the relationship between P/L^2 , s_A , and k_1 .

The relation between P/L^2 and s_A is shown in Figures 2.12 and 2.13 . The relation between P/L^2 and k_1 is shown in Figure 2.14 to Figure 2.17 .

From Equation (2.10);

$$t_{\text{opt}} = \frac{12^{\frac{1}{2}} Ls_{A}}{k_{P}^{\frac{1}{2}} \pi E} \frac{(1+2k_{1}k_{2})^{\frac{1}{2}}}{(1+6k_{1}k_{2})^{\frac{1}{2}}} -----(2.24)$$

From Equation (2.11);

$$h_{\text{opt}} = \frac{12^{\frac{1}{2}} s_{\text{A}}^{\frac{1}{2}} L}{\pi E^{\frac{1}{2}}} = \frac{(1+2k_1 k_2)^{\frac{1}{2}}}{(1+6k_1 k_2)^{\frac{1}{2}}} = -----(2.25)$$

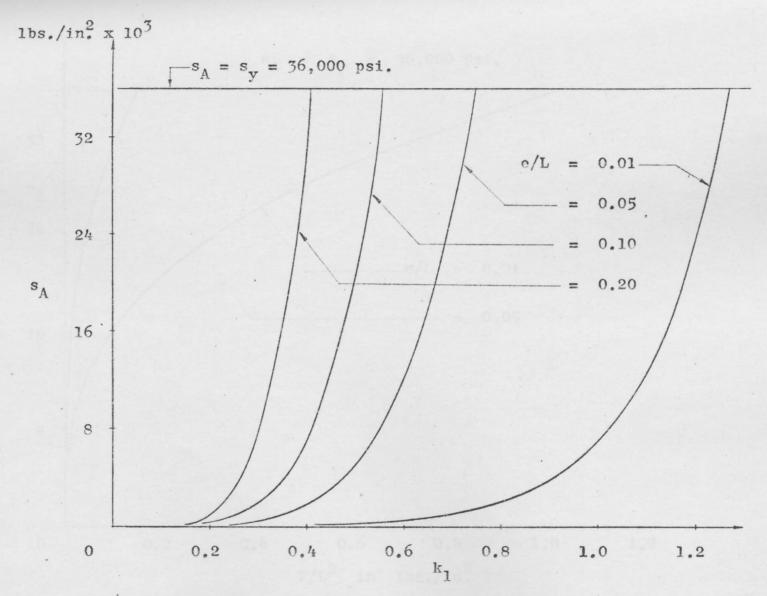


Fig. 2.11 Relation between s_A and k_1 in Equation (2.19) .

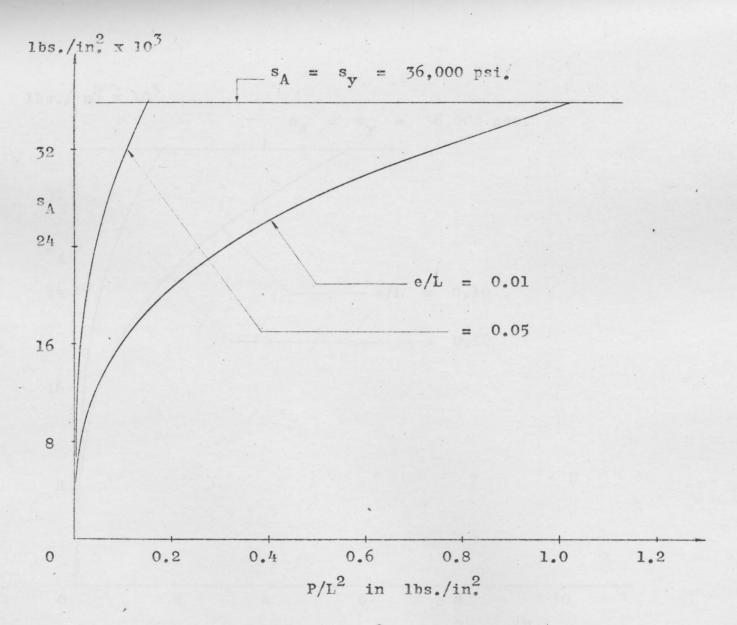


Fig. 2.12 Relation between P/L^2 and Optimum Design Stress.

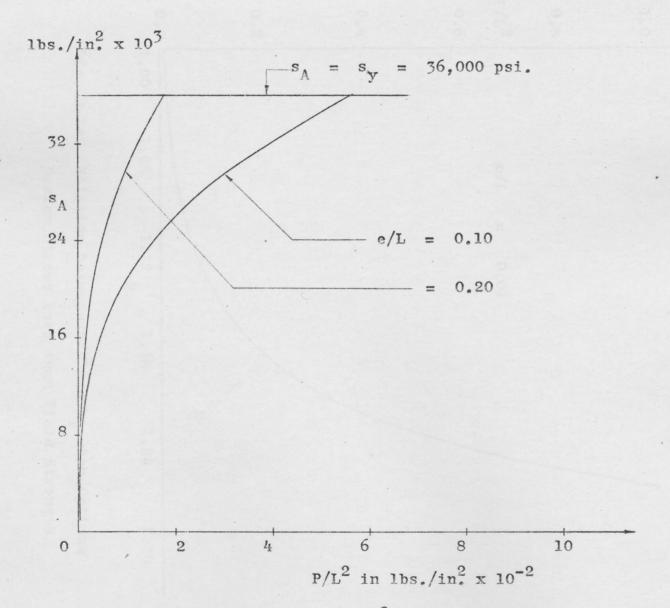


Fig. 2.13 Relation between P/L² and Optimum Design Stress.

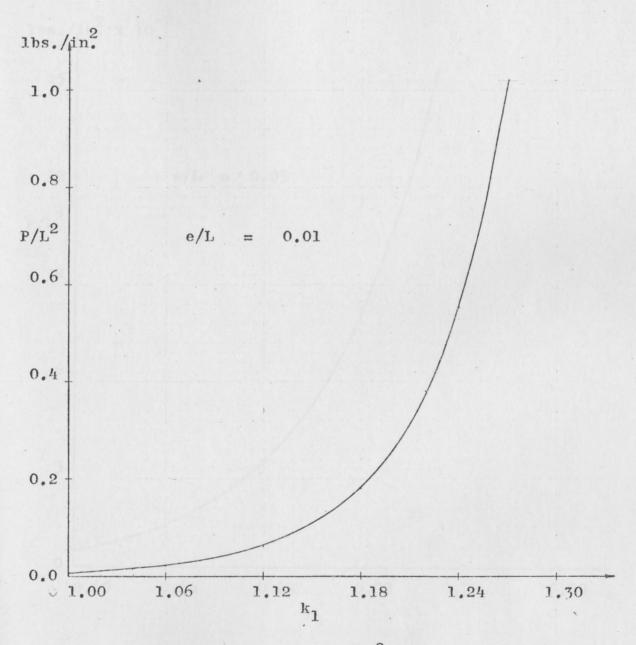


Fig. 2.14 Relation between P/L^2 and k_1 when Optimum Design Stress less than Yield Strength.

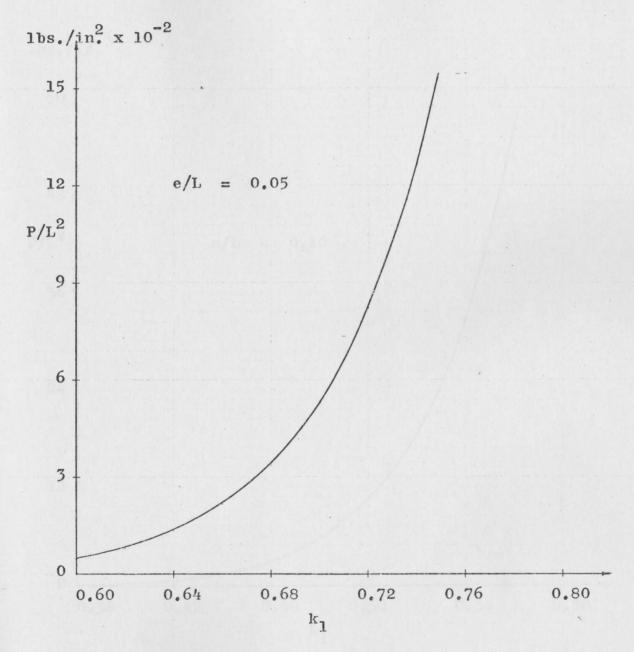


Fig. 2.15 Relation between P/L^2 and k_1 when Optimum Design Stress less than Yield Strength.

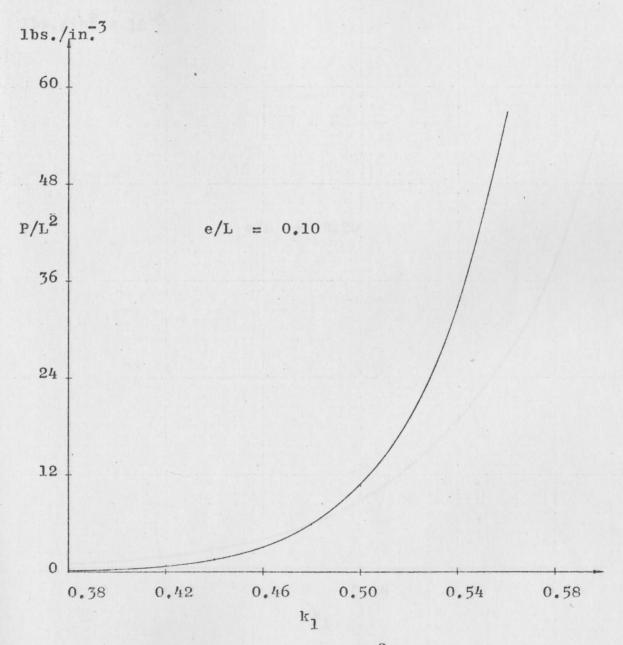


Fig. 2.16 Relation between P/L^2 and k_1 when Optimum Design Stress less than Yield Strength.

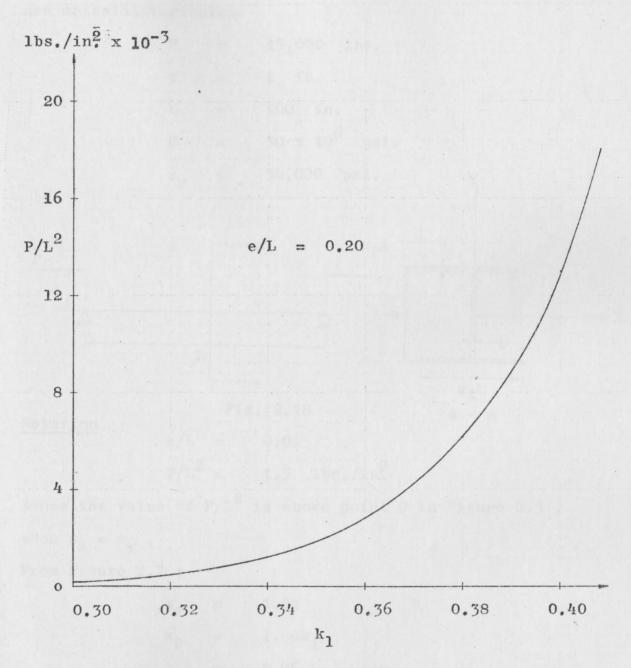
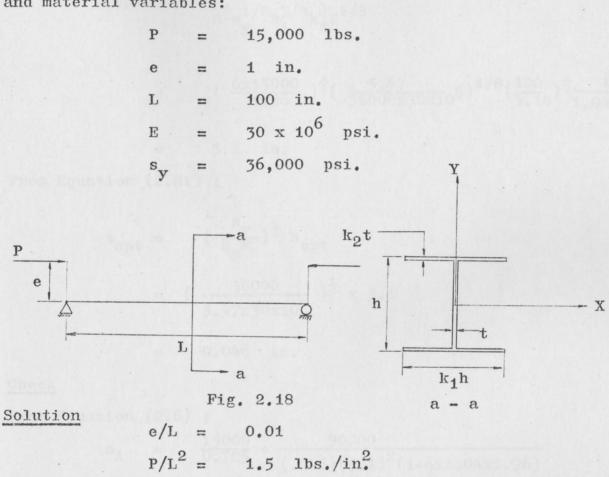


Fig. 2.17 Relation between P/L^2 and k_1 when Optimum Design Stress less than Yield Strength.

Example 2.1 Design a simply supported H-section beam-column as shown in Figure 2.18 for the following environment factors and material variables:



Since the value of P/L^2 is above point 0 in Figure 2.3, then $s_A = s_y$.

From Figure 2.7;

$$k_1 = 1.04$$
 $k_2 = 1.89k_1$
 $= 1.96$

$$h_{\text{opt}} = \frac{(6P)^{\frac{1}{4}}L^{\frac{1}{2}}k_{p}^{1/8}}{\pi^{\frac{1}{2}}s_{y}^{1/8}k_{1}^{\frac{3}{4}}k_{2}^{\frac{1}{4}}E^{1/8}}$$

$$= \left(\frac{6x15000}{1.96}\right)^{\frac{1}{2}} \left(\frac{5.47}{36000x30x10}6\right)^{\frac{1}{8}} \left(\frac{100}{3.14}\right)^{\frac{1}{2}} \frac{1}{1.043/4}$$

From Equation (2.21);

$$t_{opt} = \left(\frac{s_{y}}{k_{p}E}\right)^{\frac{1}{2}} h_{opt}$$

$$= \left(\frac{36000}{5.47 \times 30 \times 10^{6}}\right)^{\frac{1}{2}} \times 3.1$$

$$= 0.046 \text{ in.}$$

Check

$$s_A = \frac{15000}{0.725} \div \frac{90000}{(.046)(3.1)^2(1+6x1.04x1.96)}$$

$$\dot{s}_{EX} = \frac{3.14^2 \text{x} \ 30 \text{x} \ 10^6}{10000} \text{x} \frac{3.1^2}{12} \text{x} \frac{13.21}{5.07}$$

$$= 61500 \text{ psi. } 36000 \text{ psi. } ----0.\text{K}.$$

From Equation (2.4);

$$s_{Ey} = \frac{3.14^2 \times 30 \times 10^6}{10000} \times \frac{3.1^2}{6} \times \frac{1.04^3 \times 1.96}{5.07}$$

$$= 20600 \text{ psi.}$$

$$= P/A -----0.K$$

From Equation (2.1);

$$s_{Lf} = 0.385 \times 30 \times 10^6 \times (\frac{1.96 \times .046}{1.04 \times 1.55})^2$$

$$= 36000 \text{ psi.} \qquad -----0.K.$$

A =
$$.046 \times 3.1 (1+2\times1.04\times1.96)$$

= 0.725 in^2

From Figure 4.2;

$$A/L^2 = 0.725 \times 10^{-4}$$

 $A = 0.725 \text{ in}^2$ -----0.K.

Example 2.2 Design a simply supported H-section beam-column as shown in Figure 2.18 for the following environment factors and material variables:

e = 5 in.

L = 100 in.

 $E = 30 \times 10^6 \text{ psi.}$

 $s_v = 36000 \text{ psi.}$

Solution

$$e/L = 0.05$$

$$P/L^2 = 0.1 \text{ lbs./in.}^2$$

From Figure 2.4;

s_A s_v

From Figure 2.12;

$$s_{A_{opt}} = 31300 \text{ psi.}$$

From Figure 2.15;

$$k_1 = 0.73$$

$$k_2 = 2.22 k_1$$

= 1.61

From Equation (2.24);

$$t_{\text{opt}} = \frac{12^{\frac{1}{2}} \times 100 \times 31300}{1.54^{\frac{1}{2}} \times 3.14 \times 30 \times 10^{6}} \frac{(1 + 2x.73 \times 1.61)^{\frac{1}{2}}}{(1 + 6x.73 \times 1.61)^{\frac{1}{2}}}$$

$$= 0.027 \text{ in.}$$

From Equation (2.25);

$$h_{\text{opt}} = \left(\frac{12 \times 31300}{30 \times 10^6}\right)^{\frac{1}{2}} \times \frac{100}{3.14} \times \left(\frac{1 + 2 \times .73 \times 1.61}{1 \div 6 \times .73 \times 1.61}\right)^{\frac{1}{2}}$$

$$= 2.3 \text{ in.}$$

Check

$$A_{\text{opt}} = 0.027 \times 2.3 \times (1 + 2 \times .73 \times 1.61)$$

= 0.208 in²

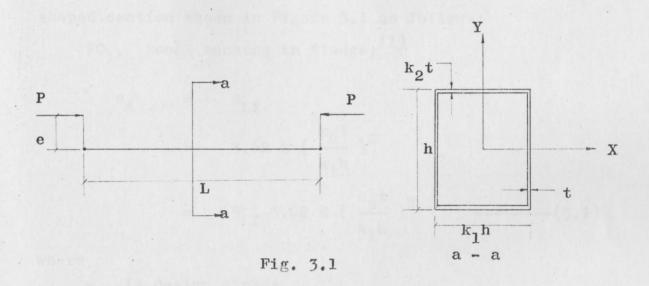
From Figure 4.3;

$$A/L^2 = 0.207 \times 10^{-4}$$

 $A = 0.207 \text{ in}^2$

CHAPTER III

RECTANGULAR SECTION



For the rectangular shaped beam-column shown in Figure 3.1;

$$I_{xx} = \frac{\sinh^{3}}{6} (1 + 3k_{1}k_{2}) -----*$$

$$I_{yy} = \frac{\sinh^{3}}{6} (k_{1}^{3}k_{2} + 3k_{1}^{2}) -----*$$

$$A = 2 + (1 + k_{1}k_{2}) -----*$$

$$r_{x}^{2} = \frac{h^{2}}{12} \frac{(1 + 3k_{1}k_{2})}{(1 + k_{1}k_{2})} ------*$$

$$r_{y}^{2} = \frac{h^{2}}{12} \frac{(k_{1}^{3}k_{2} + 3k_{1}^{2})}{(1 + k_{1}k_{2})} ------*$$

$$I_{xx} \ge I_{yy}$$

$$1 + 3k_1k_2 \ge k_1^3k_2 + 3k_1^2 \qquad -----*$$

$$M = Pe$$

The failure constraints applied to the rectangular shaped section shown in Figure 3.1 as follows:

FC₁, local bucking in flange; (1)

$$s_{A} \leq s_{Lf}$$

$$\leq 3.62 E \left(\frac{k_{2}t}{k_{1}h}\right)^{2}$$

$$= \Psi_{Lf} 3.62 E \left(\frac{k_{2}t}{k_{1}h}\right)^{2} -----(3.1)$$

where

s, is design stress

 $\mathbf{s}_{\mathbf{Lf}}$ is local buckling failure stress in flange

 $\mathbf{k_1}$, $\mathbf{k_2}$, t and h are proportional variables shown in Figure 3.1

Ψ_{If} is slack variable

FC2, local buckling in web; (4)(5)

$$s_A \leq s_{Lw}$$

$$\leq k_p E (t/h)^2$$

$$= \psi_{Lw} k_p E (t/h)^2 \qquad -----(3.2)$$

where '

 S Lw is local buckling failure stress in web k_{p} is buckling coefficient

FC₃, Euler buckling in bending axis; (4)(5)

$$s_{A} \leq s_{Ex}$$

$$\leq \frac{\pi^{2}E}{c^{2}L^{2}} \frac{h^{2}}{12} \frac{(1+3k_{1}k_{2})}{(1+k_{1}k_{2})}$$

$$= \Psi_{Ex} \frac{\pi^{2}E}{c^{2}L^{2}} \frac{h^{2}}{12} \frac{(1+3k_{1}k_{2})}{(1+k_{1}k_{2})} -----(3.3)$$

where

 $\mathbf{s}_{\mathbf{E}\mathbf{x}}$ is buckling stress in bending axis c is factor which depends on end conditions

FC4, Euler buckling in lateral direction; (1)(4)

$$s_{A1} \leq s_{Ey}$$

$$\leq \frac{\pi^2 E}{c^2 L^2} \frac{h^2}{12} \frac{(k_1^3 k_2 + 3k_1^2)}{(1 + k_1 k_2)} \qquad -----(3.4)$$

where

 \mathbf{s}_{Al} is compressive stress due to axial load only \mathbf{s}_{Ev} is buckling stress in lateral direction

FC5, design stress can not be more than yield strength;

$$s_A \leq s_y$$

$$= \psi_v s_v \qquad -----(3.5)$$

For linear materials which the applied stress in not more than yield strength, the formula for combined axial and bending stress is;

$$s_A = \frac{Mc}{T_{XX}} + \frac{P}{A}$$

$$= \frac{3Pe}{th^2(1+3k_1k_2)} + \frac{P}{2th(1+k_1k_2)} ---(3.6)$$

By the same procedure that has been used previously, the procedure proceeds indirectly by optimizing the design stress.

FC₁, FC₂, FC₃, and FC₅ are active constraints, since there are only 4 proportional variables t, h, k_1 , k_2 . Hence, FC₄ is a passive constraints.

By equating Equations (3.1) and (3.2);

$$\psi_{Lf} \ 3.62 \ E\left(\frac{k_2 t}{k_1 h}\right)^2 = \psi_{Lw} \ k_p E(t/h)^2$$
Letting
$$\psi_{Lf} = \psi_{Lw} \ by S.M.D.$$

$$k_2 = k_1 \left(\frac{k_p}{3.62}\right)^{\frac{1}{2}} -----(3.7)$$

By equating Equations (3.5) & (3.6);

$$\psi_{y}s_{y} = \frac{3Pe}{th^{2}(1+3k_{1}k_{2})} + \frac{P}{2th(1+k_{1}k_{2})}$$
 ----(3.8)

Multiplying Equation (3.2) by Equation (3.3);

$$s_A^2 = \Psi_{LW} k_p E(t/h)^2 \Psi_{EX} \frac{\pi^2 E}{c^2 L^2} \frac{h^2}{12} \frac{(1+3k_1 k_2)}{(1+k_1 k_2)}$$

From Equation (3.5);

$$\psi_{\mathbf{y}}^{2} \mathbf{s}_{\mathbf{y}}^{2} = \psi_{\mathbf{L}\mathbf{w}} \psi_{\mathbf{E}\mathbf{x}} \frac{\mathbf{k}_{\mathbf{p}} \mathbf{E}^{2} \pi^{2}}{12 \mathbf{c}^{2} \mathbf{L}^{2}} \frac{(1+3\mathbf{k}_{1} \mathbf{k}_{2})}{(1+\mathbf{k}_{1} \mathbf{k}_{2})} t^{2}$$

$$t^{2} = \frac{12 \mathbf{c}^{2} \mathbf{L}^{2} \psi_{\mathbf{y}}^{2} \mathbf{s}_{\mathbf{y}}^{2}}{\psi_{\mathbf{L}\mathbf{w}} \psi_{\mathbf{E}\mathbf{x}} \mathbf{k}_{\mathbf{p}} \pi^{2} \mathbf{E}^{2}} \frac{(1+\mathbf{k}_{1} \mathbf{k}_{2})}{(1+3\mathbf{k}_{1} \mathbf{k}_{2})} \qquad (3.9)$$

$$t = \frac{12^{\frac{1}{2}} \mathbf{c} \mathbf{L} \psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}}}{\psi_{\mathbf{L}\mathbf{w}}^{\frac{1}{2}} \psi_{\mathbf{E}\mathbf{y}}^{\frac{1}{2}} \mathbf{m} \mathbf{E}} \frac{(1+\mathbf{k}_{1} \mathbf{k}_{2})^{\frac{1}{2}}}{(1+3\mathbf{k}_{1} \mathbf{k}_{2})^{\frac{1}{2}}} \qquad (3.10)$$

By equating Equations (3.3) & (3.5);

$$\psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}} = \psi_{\mathbf{E}\mathbf{x}} \frac{\pi^{2} \mathbf{E}}{\mathbf{e}^{2} \mathbf{L}^{2}} \frac{\mathbf{h}^{2}}{12} \frac{(1+3k_{1}k_{2})}{(1+k_{1}k_{2})}$$

$$\mathbf{h}^{2} = \frac{12\mathbf{e}^{2} \mathbf{L}^{2} \psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}}}{\psi_{\mathbf{E}\mathbf{x}} \pi^{2} \mathbf{E}} \frac{(1+k_{1}k_{2})}{(1+3k_{1}k_{2})} - \dots (3.11)$$

$$\mathbf{h} = \frac{12^{\frac{1}{2}} \mathbf{c} \mathbf{L} \psi_{\mathbf{y}}^{\frac{1}{2}} \mathbf{s}_{\mathbf{y}}^{\frac{1}{2}}}{\psi_{\mathbf{E}\mathbf{x}}^{\frac{1}{2}} \pi \mathbf{E}^{\frac{1}{2}}} \frac{(1+k_{1}k_{2})^{\frac{1}{2}}}{(1+3k_{1}k_{2})^{\frac{1}{2}}} - \dots (3.12)$$

Substituting the value of t and h from Equations (3.10) and (3.12) into Equation (3.8);

$$\psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}} = \frac{\frac{3 \text{ Pe}}{12^{\frac{1}{2}} \text{cL} \psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}}} \frac{(1 + k_{1} k_{2})^{\frac{1}{2}}}{(1 + 3k_{1} k_{2})^{\frac{1}{2}}} \frac{12 \text{c}^{2} \text{L}^{2} \psi_{\mathbf{y}} \mathbf{s}_{\mathbf{y}}}{(1 + k_{1} k_{2})} \frac{(1 + k_{1} k_{2})}{(1 + 3k_{1} k_{2})} (1 + 3k_{1} k_{2})}$$

$$+ \frac{2(12)^{\frac{1}{2}} cL \psi_{y} s_{y}}{\frac{1}{2} \left(1 + k_{1} k_{2}\right)^{\frac{1}{2}}} \frac{12^{\frac{1}{2}} cL \psi_{y}^{\frac{1}{2}} s_{y}^{\frac{1}{2}}}{\frac{1}{2} \left(1 + k_{1} k_{2}\right)^{\frac{1}{2}}} \frac{12^{\frac{1}{2}} cL \psi_{y}^{\frac{1}{2}} s_{y}^{\frac{1}{2}}}{\frac{1}{2} \left(1 + k_{1} k_{2}\right)^{\frac{1}{2}}} \frac{1}{2} \left(1 + k_{1} k_{2}\right)^{\frac{1}{2}}} \left(1 + k_{1} k_{2}\right)^{\frac{1}{2}} \left(1 + k_{1} k_{2}\right)^{\frac{1}{2}}$$

Simplifying the above equation and letting $\psi_{Lw}=\psi_{Ex}=1$ and for the simple support end condition, c=1 . Thus;

$$P/L^{2} = \frac{24\psi_{y}^{3}s_{y}^{3}(1+k_{1}k_{2})^{2}}{k_{p}^{\frac{1}{2}}\left[3^{\frac{1}{2}}(e/I)^{\frac{3}{2}}E^{2}(1+3k_{1}k_{2})^{\frac{1}{2}}(1+k_{1}k_{2})^{\frac{1}{2}}+\pi^{2}E^{3/2}(1+3k_{1}k_{2})\psi_{y}^{\frac{1}{2}}s_{y}^{\frac{1}{2}}\right]} -----(3.13)$$

Letting ψ_v in Equation (3.13) be equal to unity;

$$P/L^{2} = \frac{24s_{y}^{3}(1+k_{1}k_{2})^{2}}{k_{p}^{\frac{1}{2}}\left[3^{\frac{1}{2}}(e/L)^{\frac{3}{2}}E^{2}(1+3k_{1}k_{2})^{\frac{1}{2}}(1+k_{1}k_{2})^{\frac{1}{2}}+\pi^{2}E^{3/2}(1+3k_{1}k_{2})s_{y}^{\frac{1}{2}}\right]}$$
-----(3.14)

From BUCKLING STRENGTH of METAL STRUCTURES by Bleich (5);

From Equation (3.7);

$$k_2 = k_1 (k_p/3.62)^{\frac{1}{2}}$$
 -----*

 $e/L = 0.00,$ $k_2 = k_1$
 $e/L = 0.01,$ $k_2 = 1.45 k_1$
 $e/L = 0.05,$ $k_2 = 1.71 k_1$
 $e/L = 0.10,$ $k_2 = 2.00 k_1$
 $e/L > 0.10,$ $k_2 = 2.49 k_1$

Using AISI 1025 steel;

$$E = 30 \times 10^6 \text{ psi.}$$

 $s_y = 36,000 \text{ psi.}$

Substituting the above value into Equation (3.14), the relation between P/L^2 and ${\bf k}_1$ is shown in Figures 3.2 to 3.6 for each value of e/L .

These procedures are the same as in Chapter 2. The next step is to check whether FC_4 is satisfied or not.

From Equation (3.4);

$$s_{A1} \leq \frac{\pi^{2}_{E}}{c^{2}L^{2}} \frac{h^{2}}{12} \frac{(k_{1}^{3}k_{2}+3k_{1}^{2})}{(1+k_{1}k_{2})}$$

$$\frac{P}{2\text{th}(1+k_{1}k_{2})} = \psi_{Ey} \frac{\pi^{2}_{E}}{c^{2}L^{2}} \frac{h^{2}}{12} \frac{(k_{1}^{3}k_{2}+3k_{1}^{2})}{(1+k_{1}k_{2})} ---(3.15)$$
where $\psi_{Ey} \leq 1$

Substituting the values of t and h from Equation (3.10) and Equation (3.12) into Equation (3.15); Simplifying the equation, letting $\psi_{Lw}=\psi_{Ex}=\psi_{Ey}=1$, and for the simple support end condition, c = 1. Thus;

$$\frac{P}{L^2} = \frac{24 \psi_y^{5/2} s_y^{5/2} (k_1^3 k_2 + 3k_1^2) (1 + k_1 k_2)^2}{k_p^{\frac{1}{2}} \pi^2 E^{3/2} (1 + 3k_1 k_2)^2} ---(3.16)$$

Letting Ψ_y in Equation (3.16) be equal to unity;

$$\frac{P}{L^2} = \frac{\frac{24s_y^{5/2}(k_1^3k_2 + 3k_1^2)(1 + k_1 k_2)^2}{k_p^{\frac{1}{2}\pi^2} \frac{3/2}{(1 + 3k_1 k_2)^2}} ---(3.17)$$

As in Chapter 2 , Equation (3.17) does not satisfied Equation (3.8). The relation between P/L^2 and k_1 of Equation (3.17) is shown in Figures 3.2 to 3.6 .

Since
$$I_{xx} \geq I_{yy}$$

 $1 + 3k_1k_2 \geq k_1^3k_2 + 3k_1^2 - \dots + k_1^4 + 3k_1^2$
For e/L = 0.00;
 $1 + 3k_1^2 \geq k_1^4 + 3k_1^2$
 $k_1 \leq 1$ - \dots
For e/L = 0.01;
 $1 + 4.35k_1^2 \geq 1.45k_1^4 + 3k_1^2$
 $k_1 \leq 1.18$ - \dots
For e/L = 0.05;
 $1 + 5.13k_1^2 \geq 1.71k_1^4 + 3k_1^2$
 $k_1 \leq 1.26$ - \dots

$$1 + 6k_1^2 \ge 2k_1^4 + 3k_1^2$$

$$k_1 \le 1.32 -----*$$

For e/L = 0.02;
$$1 + 7.47k_1^2 \ge 2.49k_1^4 + 3k_1^2$$

$$k_1 \le 1.40 -----*$$

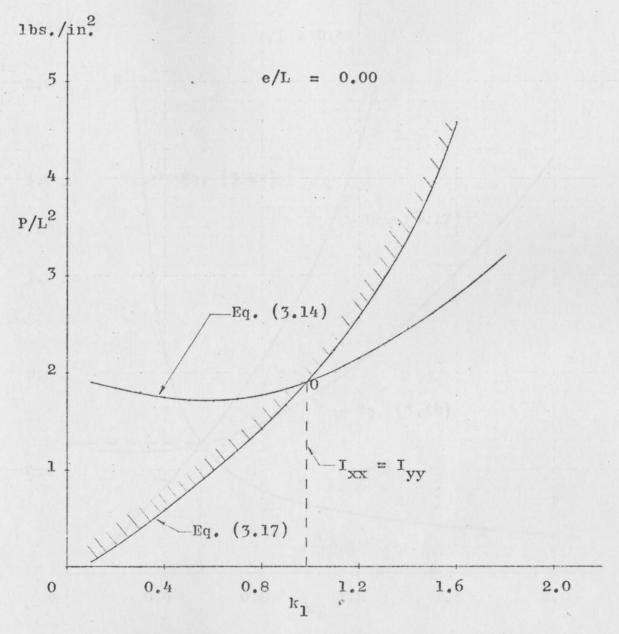


Fig. 3.2 Point 0 is the only design point when $s_A = s_y$, region which violates FC_{I_1} is shown by crosshatching.

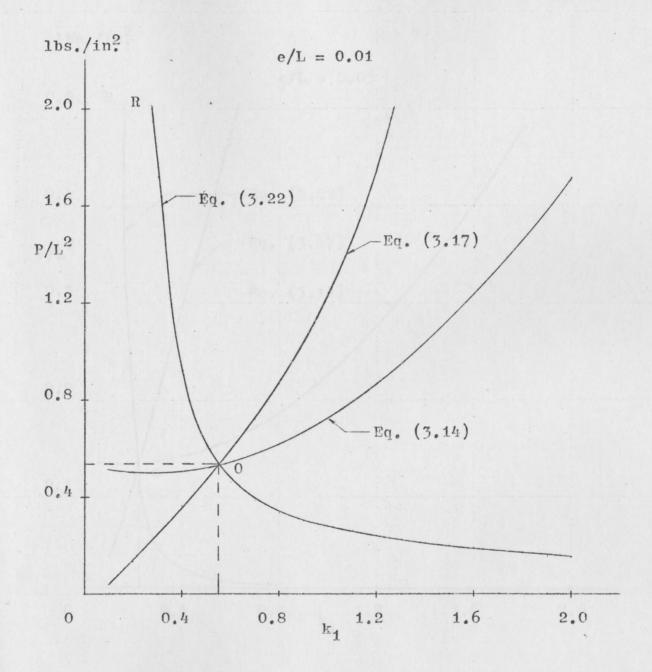


Fig. 3.3 Curve OR is design curve when $s_A = s_y$.

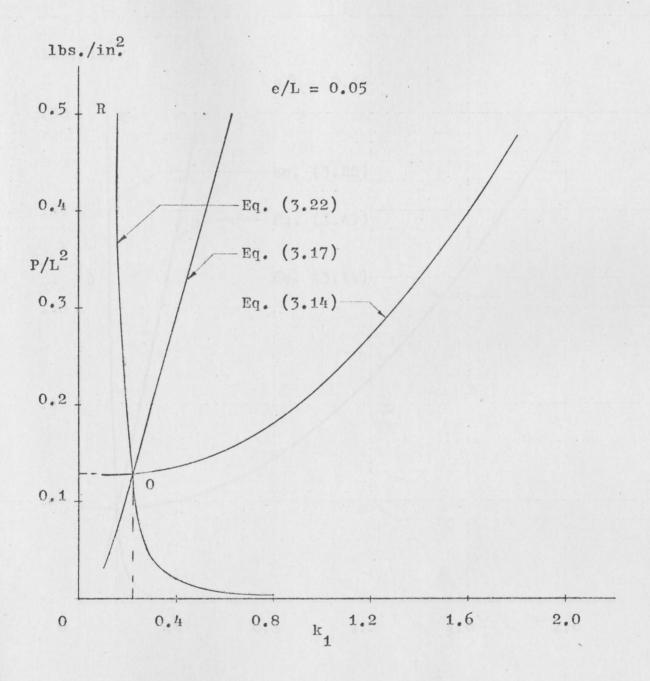


Fig. 3.4 Curve OR is design curve when $s_A = s_y$.

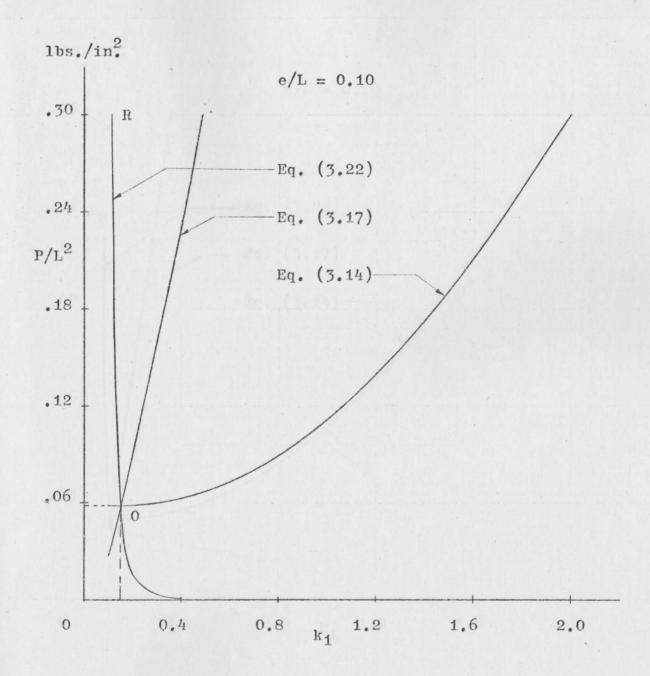


Fig. 3.5 Curve OR is design curve when $s_A = s_y$.

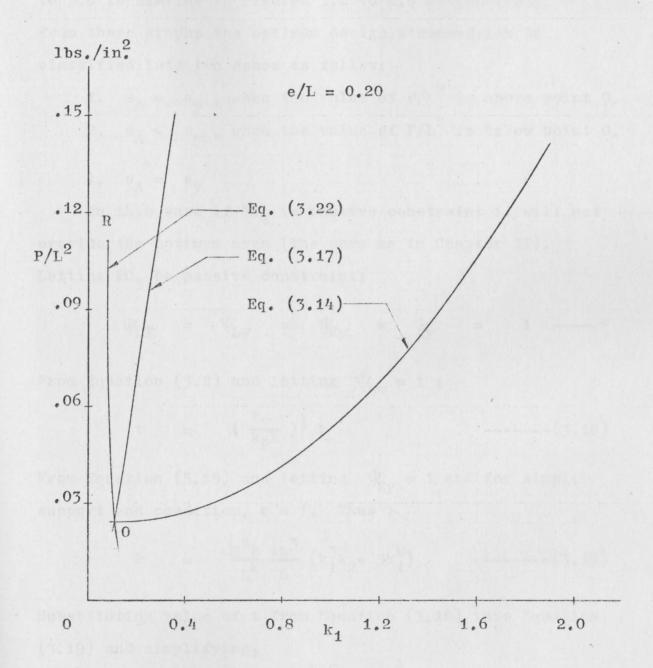


Fig. 3.6 Curve OR is design curve when $s_A = s_y$.

The relation between P/L^2 and k_1 shown in Figures 3.2 to 3.6 is similar to Figures 2.2 to 2.6 respectively. From these graphs the optimum design stressed can be classified into two cases as follow:

1. $s_A = s_y$, when the value of P/L² is above point 0.

2. $s_A < s_y$, when the value of P/L² is below point 0.

1.
$$s_A = s_y$$

In this case if FC_4 is passive constraint it will not provide the optimum area (The same as in Chapter II). Letting FC_5 be passive constraint;

$$\Psi_{Lf} = \Psi_{Lw} = \Psi_{Ey} = \Psi_{y} = 1 ----*$$

From Equation (3.2) and letting $\Psi_{Lw} = 1$;

t =
$$\left(\frac{s_y}{k_p E}\right)^{\frac{1}{2}} h$$
 ----(3.18)

From Equation (3.15) and letting $\Psi_{Ey} = 1$ and for simple support end condition, c = 1. Thus;

$$P = \frac{\pi^2 E}{L^2} \frac{th^3}{6} (k_1^3 k_2 + 3k_1^2) \qquad -----(3.19)$$

Substituting value of t from Equation (3.18) into Equation (3.19) and simplifying;

$$h = \left[\frac{6PL^{2}k_{p}^{\frac{1}{2}}s_{v}^{\frac{1}{2}}}{\pi^{2}E^{\frac{1}{2}}(k_{1}^{3}k_{2}+3k_{1}^{2})}\right]^{\frac{1}{4}}$$
 ----(3.20)

Substituting value of h from Equation (3.20) into Equation

(3.18)
$$t = \left[\frac{6PL^2k_p^{\frac{1}{2}}s_y^{\frac{1}{2}}}{\pi^2E \left(k_1^3k_2 + 3k_1^2\right)} \right]^{\frac{1}{4}} \left(s_y/k_pE\right)^{\frac{1}{2}} - - - - (3.21)$$

Substituting values of t and h from Equations (3.20) and (3.21) into Equation (3.6) and simplifying;

$$s_{y} = \frac{(P/L^{2})^{\frac{1}{2}}E^{3/4}(k_{1}^{3}k_{2}+3k_{1}^{2})^{\frac{1}{2}}\pi k_{P}^{\frac{1}{4}}}{24^{\frac{1}{2}}s_{y}^{\frac{1}{2}}(1+k_{1}k_{2})}$$

$$+ \frac{3(P/L^{2})^{\frac{1}{2}}(e/L)E^{7/8}(k_{1}k_{2}+3k_{1})^{3/4}\pi^{3/2}k_{P}^{1/8}}{6^{3/4}s_{y}^{1/8}(1+3k_{1}k_{2})}$$

The relation between P/L^2 and k_1 in Equation (3.22) was obtained by writing a computer program (See Appendix A) and are shown in Figures 3.3 to 3.6. For designing the relation between P/L^2 and k_1 is plotted on more accurate scale shown in Figures 3.7 to 3.10.

From Equation (3.20)
$$h_{\text{opt}} = \begin{bmatrix} \frac{6PL^2k_{\text{ps}}^{\frac{1}{2}}k_{\text{y}}^{\frac{1}{2}}}{\pi^2E^{\frac{1}{2}}(k_{1}^{3}k_{2}+3k_{1}^{2})} \end{bmatrix}^{\frac{1}{4}}$$

From Equation (3.21);

$$t_{opt} = (s_y/k_p E)^{\frac{1}{2}} h_{opt}$$
 ----*

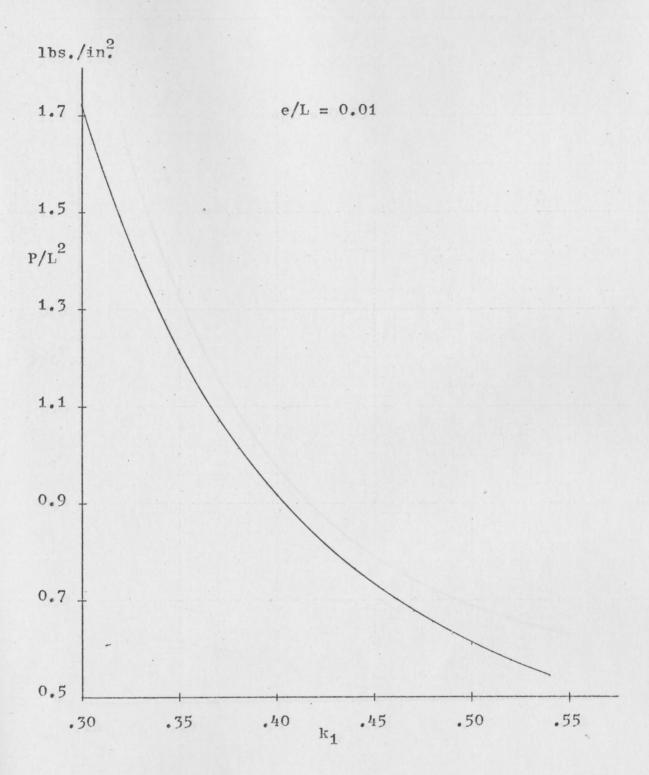


Fig. 3.7 Relation between P/L^2 and k_1 in Equation (3.22) when $s_A = s_y$.

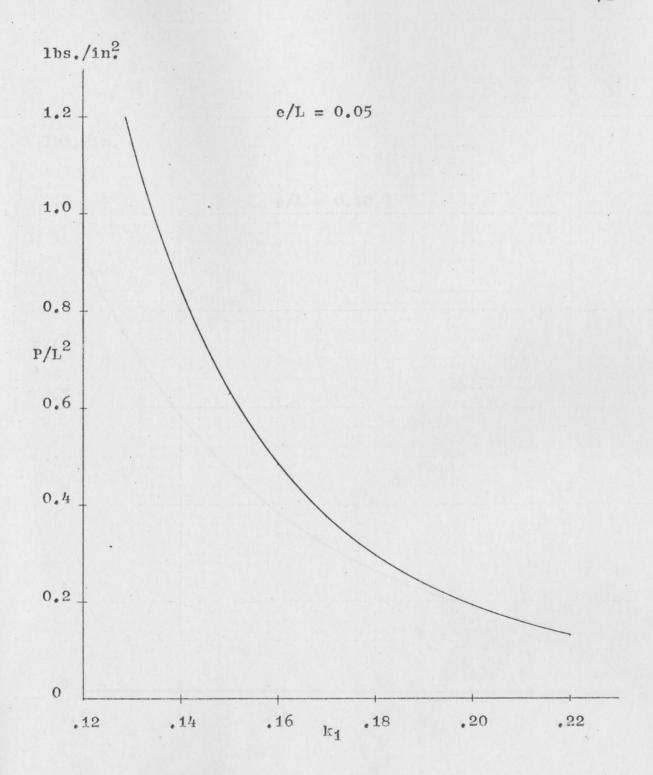


Fig. 3.8 Relation between P/L^2 and k_1 in Equation (3.22) when $s_A = s_y$.

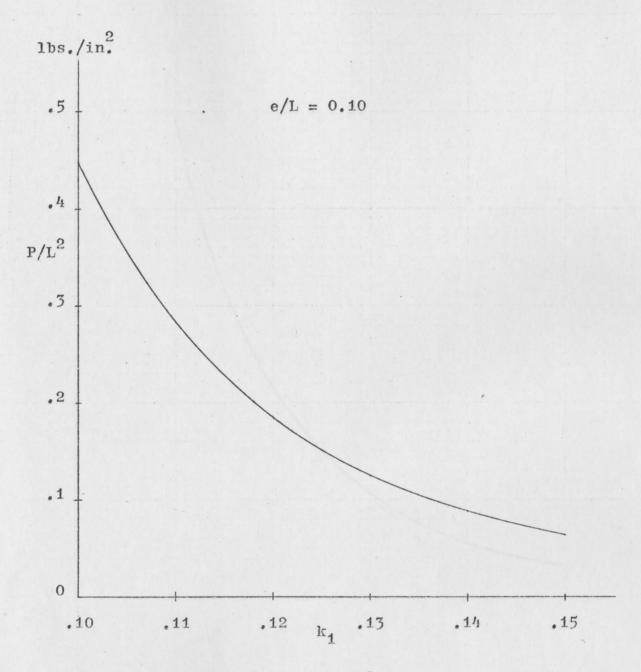


Fig. 3.9 Relation between P/L^2 and k_1 in Equation (3.22) when $s_A = s_y$.

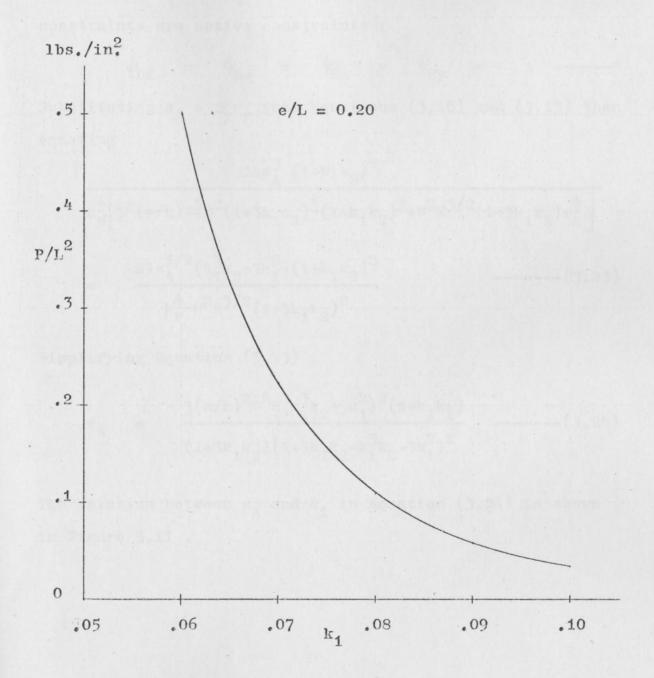


Fig. 3.10 Relation between P/L^2 and k_1 in Equation (3.22) when $s_A = s_y$.

In this case FC_5 is passive constraint; the other constraints are active constraints;

$$\Psi_{Lf} = \Psi_{Lw} = \Psi_{Ex} = \Psi_{Ey} = 1$$

Substituting $s_A = \psi_y s_y$ into Equations (3.16) and (3.13) then equating

$$\frac{24s_{A}^{3} (1+k_{1}k_{2})^{2}}{k_{p}^{\frac{1}{2}} \left[3^{\frac{1}{2}}(e/L)\pi^{3}E^{2}(1+3k_{1}k_{2})^{\frac{1}{2}}(1+k_{1}k_{2})^{\frac{1}{2}}+\pi^{2}E^{3/2}(1+3k_{1}k_{2})s_{A}^{\frac{1}{2}}\right]} = \frac{24s_{A}^{5/2} (k_{1}^{3}k_{2}+3k_{1}^{2})(1+k_{1}k_{2})^{2}}{k_{p}^{\frac{1}{2}} \pi^{2}E^{3/2}(1+3k_{1}k_{2})^{2}} -----(3.23)$$

Simplifying Equation (3.23);

$$s_{A} = \frac{3(e/L)^{2}\pi^{2}E(k_{1}^{3}k_{2}+3k_{1}^{2})^{2}(1+k_{1}k_{2})}{(1+3k_{1}k_{2})(1+3k_{1}k_{2}-k_{1}^{3}k_{2}-3k_{1}^{2})^{2}} -----(3.24)$$

The relation between s_A and k_1 in Equation (3.24) is shown in Figure 3.11 .

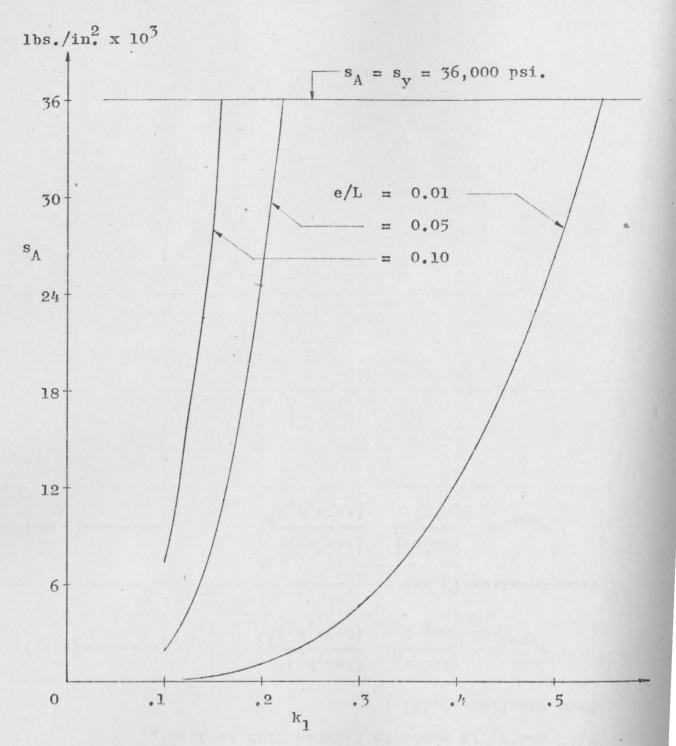


Fig. 3.11 Relation between \boldsymbol{s}_{A} and \boldsymbol{k}_{1} in Equation (3.24) .

Substituting the values of s_A and k_1 from Equation (3.24) into Equation (3.13) or Equation (3.16), will yield the relationship between P/L^2 , s_A and k_1 . The relation between k_1 , P/L^2 and s_A is shown in Figures 3.12 to 3.16.

From Equation (3.10);

$$t_{opt} = \frac{12^{\frac{1}{2}}Ls_A}{\pi k_p^{\frac{1}{2}}E} \frac{(1+k_1k_2)^{\frac{1}{2}}}{(1+3k_1k_2)^{\frac{1}{2}}} -----(3.25)$$

From Equation (3.12);

$$h_{\text{opt}} = \frac{12^{\frac{1}{2}} L s_{A}^{\frac{1}{2}}}{\pi E^{\frac{1}{2}}} \frac{(1+k_{1}k_{2})^{\frac{1}{2}}}{(1+3k_{1}k_{2})^{\frac{1}{2}}} -----(3.26)$$

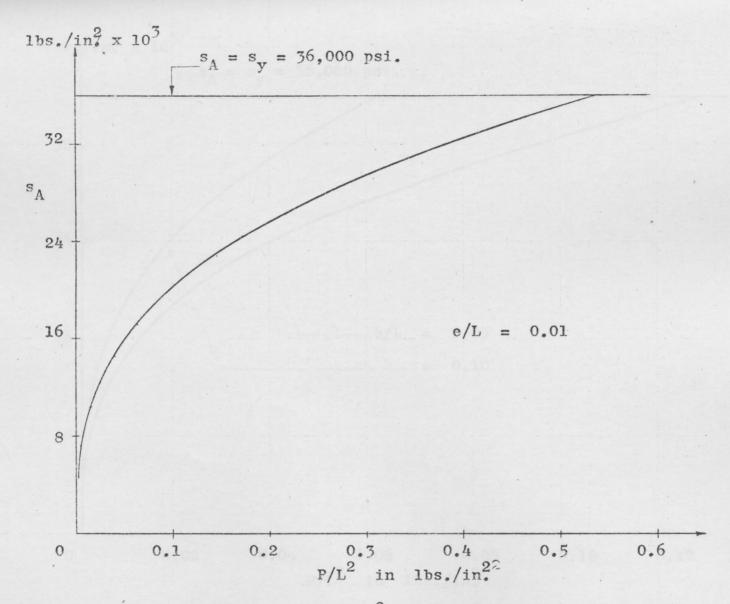


Fig. 3.12 Relation between P/L^2 and Optimum Design Stress.

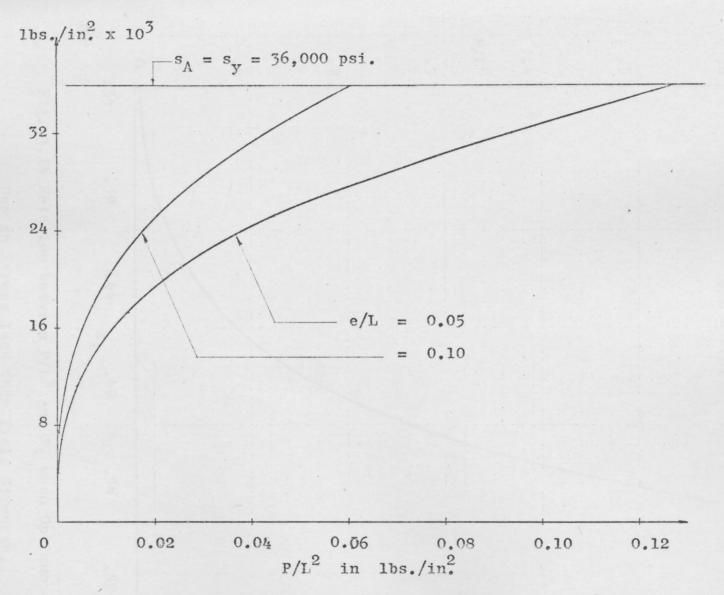


Fig. 3.13 Relation between P/L^2 and Optimum Design Stress.

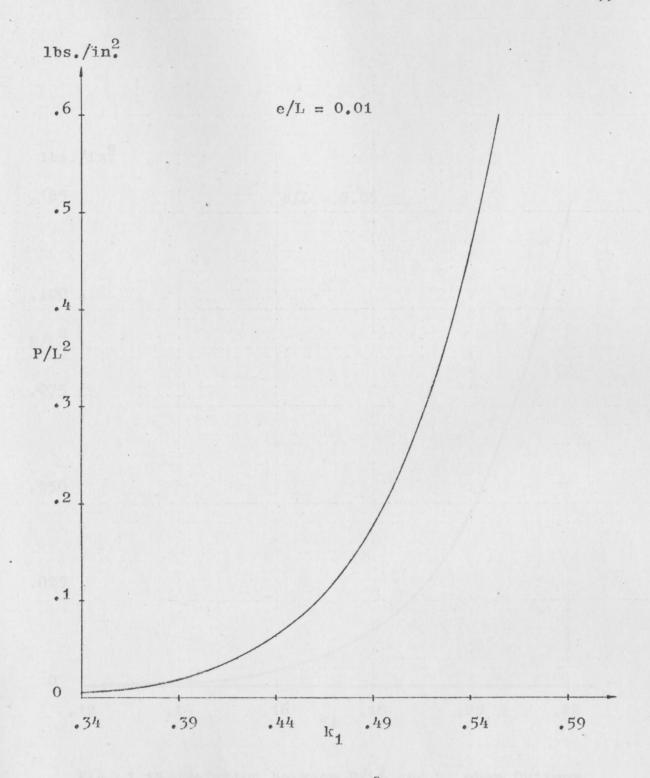


Fig. 3.14 Relation between P/L^2 and k_1 when Optimum Design Stress less than Yield Strength.

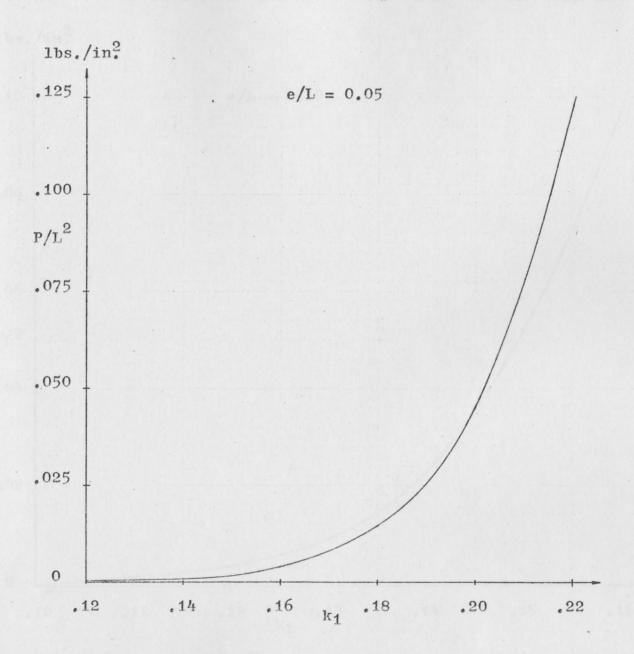


Fig. 3.15 Relation between P/L^2 and k_1 when Optimum Design Stress less than Yield Strength.

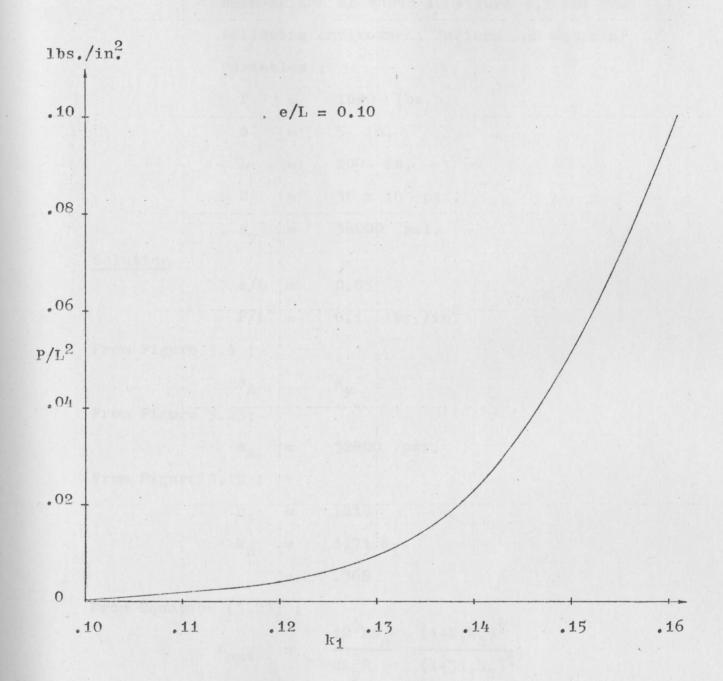


Fig. 3.16 Relation between P/L and k when Optimum Design Stress less than Yield Strength.

Example 3.1 Design a simply supported rectangular tube beam-column as shown in Figure 3.1 for the following environment factors and material variables:

$$P = 1000 lbs.$$

$$e = 5 in.$$

$$E = 30 \times 10^6 \text{ psi.}$$
 $s_y = 36000 \text{ psi.}$

$$s_v = 36000 \text{ psi}$$

Solution

$$e/L = 0.05$$

$$P/L^2 = 0.1 \text{ lbs./in.}^2$$

From Figure 3.4;

From Figure 3.13;

$$s_A = 32800 \text{ psi.}$$

From Figure 3.15;

$$k_1 = .215$$

$$k_2 = 1.71 k_1$$

From Equation (3.25);

$$t_{\text{opt}} = \frac{12^{\frac{1}{2}} Ls_{A}}{\pi k_{p}^{\frac{1}{2}} E} = \frac{(1+k_{1}k_{2})^{\frac{1}{2}}}{(1+3k_{1}k_{2})^{\frac{1}{2}}}$$

$$= \left(\frac{12}{10.3}\right)^{\frac{1}{2}} \frac{32800 \times 100}{3.14 \times 30 \times 10} \left(\frac{1+0.215 \times 0.368}{1+3 \times .215 \times .368}\right)^{\frac{1}{2}}$$

From Equation (3.26);

$$h_{\text{opt}} = \frac{12^{\frac{1}{2}} \text{Ls}_{\text{A}}^{\frac{1}{2}}}{\pi \text{E}^{\frac{1}{2}}} \frac{(1+k_1 k_2)^{\frac{1}{2}}}{(1+3k_1 k_2)^{\frac{1}{2}}}$$

$$= (\frac{12x32800}{30x10^6})^{\frac{1}{2}} \frac{100}{3 \cdot 14} (\frac{1+0.215x0.368}{1+3x.215x.368})^{\frac{1}{2}}$$

$$= 3.42 \text{ in.}$$

Check

From Figure 3.1;

$$A = 2 th(1+k_1k_2)$$

$$= 2x0.0352x3.42(1+0.215x0.368)$$

$$= .20.262 in2$$

From Figure 4.2;

$$A/L^2 = 0.260 \times 10^{-l_1}$$
 $A = 0.260 \text{ in}^2$ -----0.K

From Equation (3.1);

$$s_{Lf} = 3.62E(\frac{k_2t}{k_1h})^2$$
 -----*
$$= 3.62x30x10^6 (\frac{0.368x0.0352}{0.215x3.42})^2$$

$$= 33000 psi. -----0.K$$

From Equation (3.3) and for simple support end condition,

$$c = 1;$$

$$s_{Ex} = \frac{\pi^{2}E}{L^{2}} \frac{h^{2}}{12} \frac{(1+3k_{1}k_{2})}{(1+k_{1}k_{2})}$$

$$= \frac{(3.14x3.42)^{2}x30x10^{6}}{10^{4}x12} (\frac{1+0.237}{1+0.079})$$

$$= 33000 \text{ psi.}$$

From Equation (3.4) and for simple support end condition,

From Equation (3.6);

CHAPTER IV

COMPARISON OF RESULTS

Circular Tube Section

From Figure 1.1;

$$A = \pi Dt$$
 -----(4.1)

When the optimum design stress is less than the yield strength, $D_{\rm opt}$ and $t_{\rm opt}$ are obtained from Equations (1.17) and (1.18).

Substituting Dopt and topt into Equation (4.1);

$$A_{\text{opt}} = \pi(\psi_{\mathbf{y}} s_{\mathbf{y}}/\text{KE}) (8\psi_{\mathbf{y}} s_{\mathbf{y}}/\text{E}) \frac{L^{2}}{\pi^{2}}$$

$$(\frac{A}{L^{2}})_{\text{opt}} = \frac{8}{\pi K} (\frac{\psi_{\mathbf{y}} s_{\mathbf{y}}}{E})^{2} \qquad -----(4.2)$$

Using the relation between ψ_y and P/L^2 from Equation (1.16) as data in running the computer program* for Equation (4.2), the relation between P/L^2 and A/L^2 were obtained and are shown in Figure (4.1) to Figure (4.4).

When the optimum design stress equals the yield strength, $D_{\rm opt}$ and $t_{\rm opt}$ are obtained from Equations (1.19) and (1.20). From Equation (1.19) ;

$$t = \frac{s_y^D}{KE} \qquad -----(4.3)$$

From Equation (1.20);

$$s_{y} = \frac{4Pe + DP}{\pi D^{2}t}$$

^{*}See computer program in Appendix A

Substituting the value of t from Equation (4.3) into this equation and rearranging;

$$P/L^2 = \frac{\pi s_y^2 (D/L)^3}{KE(4e/L + D/L)}$$
 ----(4.4)

Substituting the value of t from Equation (4.3) into Equation (4.1); $A = \frac{\pi s_y D^2}{KE}$

$$A/L^2 = \frac{\pi s_y(D/L)^2}{KE}$$
 ----(4.5)

From Equations (4.4) and (4.5) the relation between P/L^2 , D/L and A/L^2 is obtained by running the computer program. The relation between P/L^2 and A/L^2 is shown in Figure (4.1) to Figure (4.4).

H - Section

From Figure 2.1;

$$A = th(1+2k_1k_2)$$
 ----(4.6)

When the optimum design stress is less than the yield strenght, $t_{\rm opt}$ and $h_{\rm opt}$ are obtained from Equations (2.24) and(2.25) . Substituting values of $t_{\rm opt}$ and $h_{\rm opt}$ into Equation (4.6) and simplifying ;

$$(A/L^2)_{\text{opt}} = \frac{12 \text{ s}_A^{3/2} (1+2k_1k_2)^2}{k_p^{\frac{1}{2}} \pi^2 E^{3/2} (1+6k_1k_2)} -----(4.7)$$

Using the relation between P/L^2 and k_1 shown in Figures 2.14 to 2.16 as data in running the computer program for Equation

(4.7) the relation between P/L^2 and A/L^2 were obtained and are shown in Figures 4.1 to 4.4.

When the optimum design stress equals the yield strength, $t_{\rm opt}$ and $t_{\rm opt}$ are obtained from Equations (2.20) and (2.21). Substituting values of $t_{\rm opt}$ and $t_{\rm opt}$ into Equation (4.6) and simplifying;

 $(A/L^{2})_{\text{opt}} = \frac{6^{\frac{1}{2}}(P/L^{2})^{\frac{1}{2}}(s_{y}/k_{p})^{\frac{1}{2}}(1+2k_{1}k_{2})}{\pi E^{3/4} k_{1}^{3/2} k_{2}^{1/2}} ----(4.8)$

The relation between P/L^2 and k_1 from Equation (2.22) was used to obtain relation between A/L^2 and P/L^2 in Equation (4.8). The results are shown in Figure 4.1 to Figure 4.4.

In this case if FC_3 is the active constraint and FC_4 is the passive constraint the relation between P/L^2 and A/L^2 will be obtained as follows:

From Equation (2.10) and letting $\psi_y=\psi_{Ex}=\psi_{Lw}=1$ and for simple support end condition, c=1 . Thus ;

t =
$$\frac{12^{\frac{1}{2}} Ls_{y}}{k_{p}^{\frac{1}{2}} \pi E} \frac{(1+2k_{1}k_{2})^{\frac{1}{2}}}{(1+6k_{1}k_{2})^{\frac{1}{2}}} -----(4.9)$$

From Equation (2.11); $h = \frac{12^{\frac{1}{2}} s_{2}^{\frac{1}{2}} L}{\pi E^{\frac{1}{2}}} \frac{(1+2k_{1}k_{2})^{\frac{1}{2}}}{(1+6k_{1}k_{2})^{\frac{1}{2}}} -----(4.10)$

Substituting values of t and h from Equations (4.9) and (4.10) into Equation (4.6) and simplifying;

^{*}See computer program in Appendix A

$$(A/L^{2}) = \frac{12s_{y}^{3/2}}{k_{p}^{\frac{1}{2}\pi^{2}E^{3/2}}} \frac{(1+2k_{1}k_{2})^{2}}{(1+6k_{1}k_{2})} -----(4.11)$$

Using the relation between P/L^2 and k_1 from Equation (2.13) to obtain the relation between A/L^2 and P/L^2 in Equation (4.11), the relations between P/L^2 and A/L^2 in Equations (4.8) and (4.11) are plotted on same figure for comparision, Figure 4.5 and Figure 4.6 for e/L equal to 0.01 and 0.05. It will be seen that if FC_3 is an active constraint, optimum area will not be obtained.

Rectangular Tube Section

From Figure 3.1;

$$\Lambda = 2 th(1+k_1k_2) \qquad ----(4.12)$$

When optimum design stressed is less than yield strength, $t_{\rm opt}$ and $h_{\rm opt}$ are obtained from Equations (3.25) and (3.26). Substituting values of $t_{\rm opt}$ and $h_{\rm opt}$ into Equation (4.12) and simplifying:

and simplifying;

$$(A/L^2)_{\text{opt}} = \frac{24s_A^{3/2}}{k_p^{\frac{1}{2}}\pi^2 E^{3/2}} \frac{(1+k_1k_2)^2}{(1+3k_1k_2)} -----(4.13)$$

Using the relation between P/L^2 and k_1 shown in Figures 3.14 to 3.16 as data in running the computer program for Equation (4.13) the relation between P/L^2 and A/L^2 was obtained and is shown in Figures 4.1 to 4.4.

When the optimum stress equals the yield strength, $t_{\rm opt}$ and $h_{\rm opt}$ are obtained from Equations (3.20) and (3.21)

Then, substituting values of t_{opt} and h_{opt} into Equation (4.12) and simplifying ;

$$(A/L^{2})_{\text{opt}} = \frac{24^{\frac{1}{2}}(P/L)^{\frac{1}{2}}(s_{y}/k_{p})^{\frac{1}{4}}(1+k_{1}k_{2})}{\pi E^{3/4}(k_{1}^{3}k_{2}+3k_{1}^{2})^{1/2}} ----(4.14)$$

Using the relation between P/L^2 and k_1 from Equation (3.22) for running the computer program (see Appendix A), the relation was obtained between P/L^2 and A/L^2 in Equation (4.11) and is shown in Figure 4.1 to 4.4.

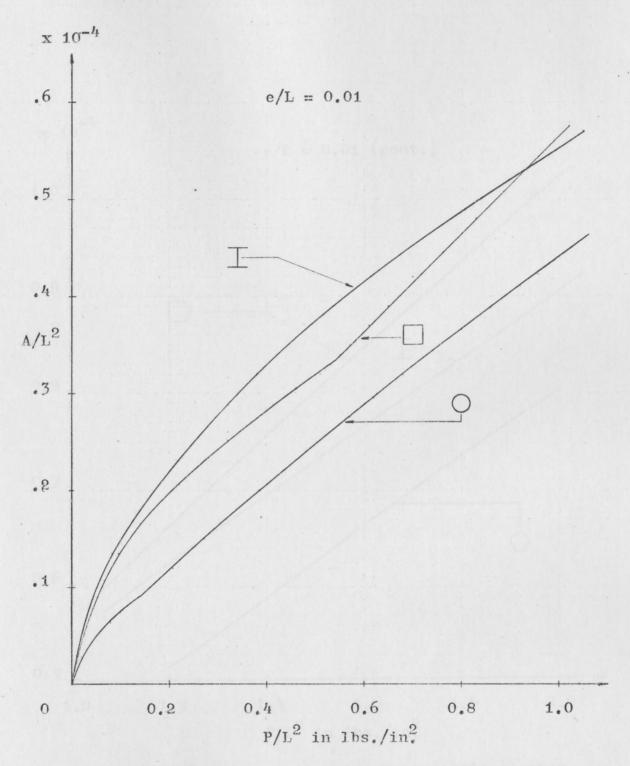


Figure 4.1 Form comparison of cross sectional area

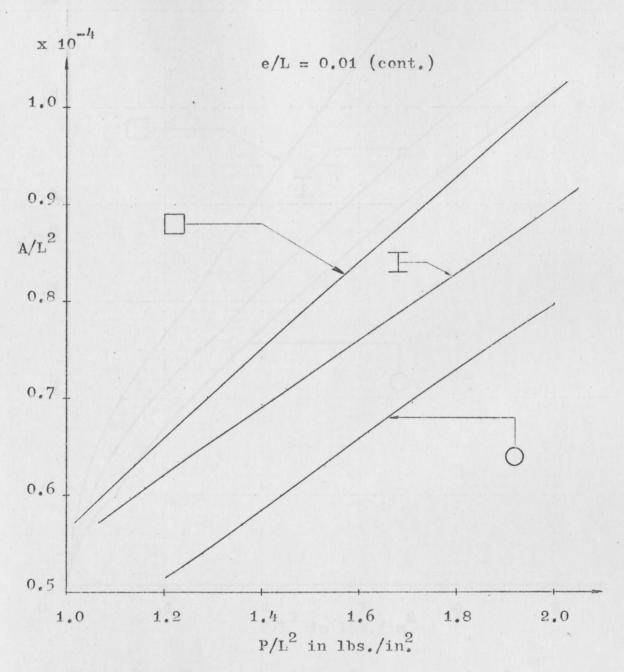


Figure 4.2 Form comparison of cross sectional area

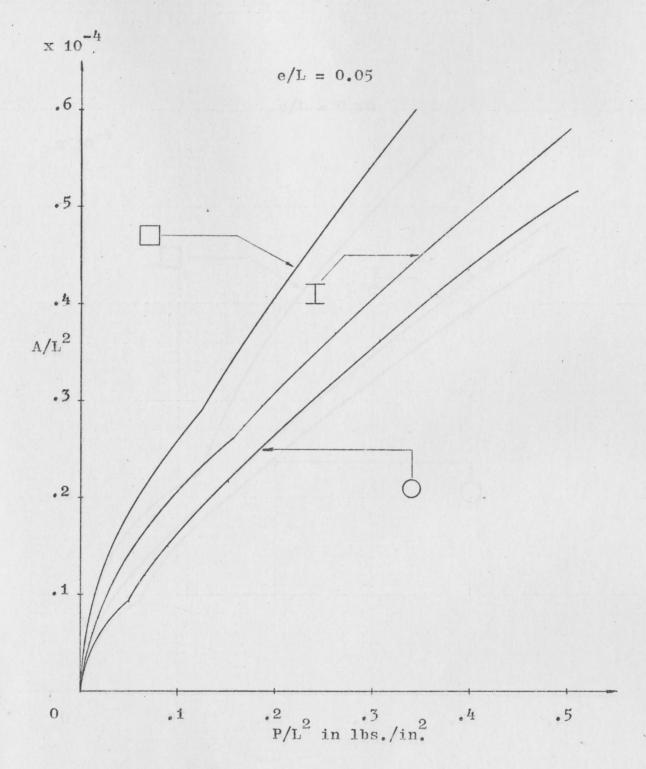


Figure 4.3 Form comparison of cross sectional area

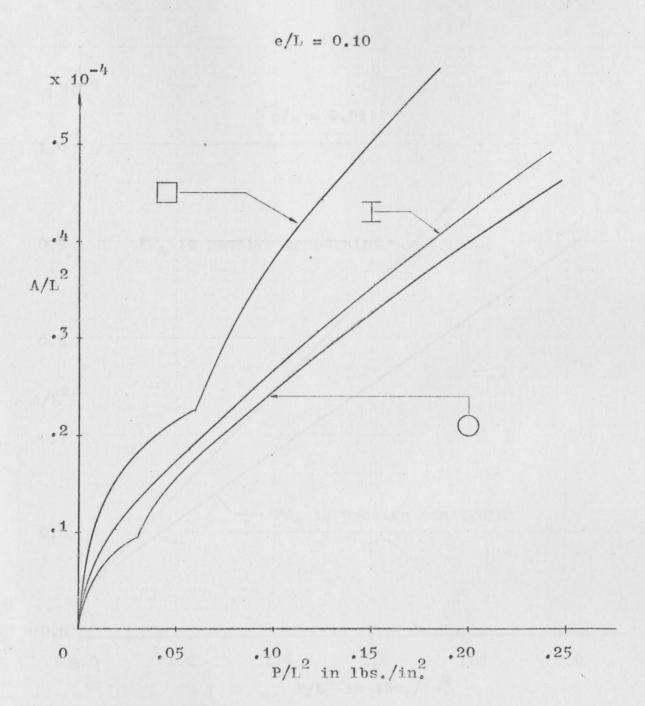


Figure 4.4 Form comparison of cross sectional area

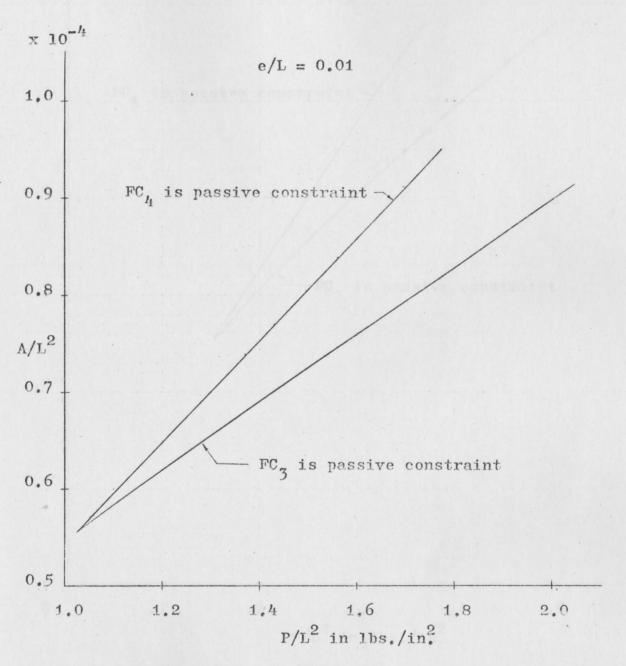


Figure 4.5 The proof that FC₃ is active constraint optimum cross sectional area will not be obtained.

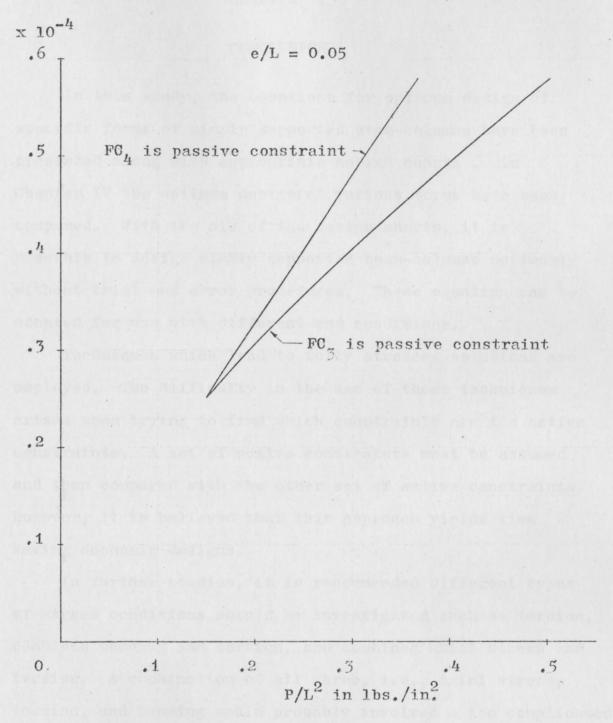


Figure 4.6 The proof that FC₃ is active constraint optimum cross sectional area will not be obtained.

CHAPTER V

CONCLUSION

In this study, the equations for optimum design of specific forms of simply supported beam-columns have been presented along with appropriate design charts. In Chapter IV the optimum designs of various forms have been compared. With the aid of the design charts, it is possible to design simply supported beam-columns optimumly without trial and error procedures. These equation can be adapted for use with different end conditions.

Techniques which lead to fully stressed solutions are employed. The difficulty in the use of these techniques arises when trying to find which constraints are the active constraints. A set of active constraints must be assumed and then compared with the other set of active constraints. However, it is believed that this approach yields time saving economic designs.

In further studies, it is recommended different types of stress conditions should be investigated such as torsion, combined bending and torsion, and combined axial stress and torsion. A combination of all three, i.e., axial stress, torsion, and bending would probably involved a too complicated procedure and other optimum techniques would need to be employed.

APPENDIX A

FORTAN COMPUTER PROGRAM

The symbols use in the computer program are as following:

AL2	=	A/L^2
C, PL2	=	P/L^2
CK1	=	k ₁
CK2	п	k ₂ /k ₁
CKP.	=	kp
DL	=	D/L
S	=	e/L
SA	=	SA
X	=	Ψ

C	OPTIMUM STRUCTURAL DESIGN		
C	CIRCULAR SECTION S & C RELATIONSHIP	FOR	X = 1
	.DO 20 K=1,35,1		
	P=K		
	C=0.0005*P		
	S=(1.0-3.04*C)/388.0/C		
100	FORMAT(2F15.5)		
20	WRITE(6,100)C,S		
	STOP		
	END		

EPIL

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C OPTIMUM STRUCTURAL DESIGN
C CIRCLEAR SECTION X & C RELATIONSHIP WHEN S=0
LO 20 K=1.35.1
P=K
C=0.01*P
X=(3.04*C)**0.3333
100 FORMAT(2F15.5)
20 WRITE(6.100)C.X
STOP

DATE = 72091

END

1001

002

1003

1004

1005

1006

0008

1009

1010

0011

C OPTIMUM STRUCTURAL DESIGN C CIRCULAR SECTION X & C RELATIONSHIP FOR S=.01 100 · FORMAT(3F15.5) C=0.01 101 DO 20 K=1,100,1 P=K X=0.01*P A=X**3.5-3.04*C*X**0.5-3.88*C 20 WRITE(6,100)C, X, A C=C+0.01 IF(C-0.35)101,102,102 102 STOP

END

C	OPTIMUM STRUCTURAL DESIGN			
C	CIRCULAR SECTION X & C RELATIONSHIP	FOR	5=.05	
100	FORMAT(3F15.5)			
	C=0.01			
101	DO 20 K=1,100,1			
	P=K			
	X=0.01*P			
	A=X**3.5-3.04*C*X**0.5-19.4*C			
20	WRITE(6,100)C,X,A			
	C=C+0.01			
	1F(C-0.35)101,102,102			
102	STOP			

END

C	OPTIMUM STRUCTURAL DESIGN	
C	CIRCULAR SECTION X & C RELATIONSHIP FOR	S=.1
100	:FORMAT(3F15.5)	
	C=0.01	
101	DO 20 K=1,100,1	
	P=K	
	X=0.01*P	
	A=X**3.5-3.04*C*X**0.5-38.8*C	
20	WRITE(6,100)C, X, A	
	C=C+0.01	
	IF(C-0.35)101,102,102	
102	STOP	

103 DATE = 72230a LEVEL 20 MAIN 20/03/14 .. PELATION BETWEEN AREA SPL2 WHEN SA < SY OPTIMIN STRUCTURAL DESIGN CIRCULAR TUBE SECTION 100 FORMAT (5F-15.5) PEAD(5.100, END=99)S, PL2, X 101 AL2=8.0*(X*36000.0)**2.0/(0.4*30000000.0**2.0*3.14)*10000.0 WRITE(6,100)5,PL2,AL2 GG TO 101 00 STOP END

14/56/21

C PPTIMUM STRUCTURAL DESIGN CIRCULAR TUBE SECTION

C RELATION BETWEEN AREA EPL2 WHEN SA = SY

100 FORMAT(5F15.5)

101 RFAD (5, 100, END=99)S DU 20 K=10, 200, 2

P=K

DL =0.001*P

PL2=36000.0**2.0*3.14*DL**3.0/(0.4*30000000.0)/(4.0*S+DL)

AL2=3.14*DL**2.0*36000.0/{0.4*30000000.01*10000.0

20 WRITE (6, 100) S, DL, PL2, AL2

GO TO 101

99 STOP END

e unever.	Oley COMPUTER CENTER			
G LEVEL	20	MAIN	DATE = 72234	19/15/35
Language Control of the Control of t	RELATION BETWEEN FCRMAT(5F15.5) READ(5,100,END=29)5	P P SI-Y=1 P P P P SI-Y=1 R P SI-Y=1 P P P SI-Y=1 P P SI-Y=1 P	/L**2=C , K1=CK1	
	14**2.0*30000000.0**	*1.5*(1.0+6.0*CK1** *30000000.0**2.0*(1	**2.0*CK2)**2.07CKP* *2.0*CK2)*12.0**0.5*3 .0+5.0*CK1**2.0*CK2)	6000.0**0
20	WRITE(6,100)S,CK1,C			
99	END			•

MAIN

DATE = 72234

19/25/35

UPTIMUM STRUCTURAL DESIGN H-SECTION C C & K1 RELATION FOR ALL PSI=1 P/L * * 2 = C K1=CK1 RELATION PETWEEN P/L**2 & KI IN EQUATION (2.17) FURMAT(5F15.5) 100 101 READ (5, 100, END=99)S, CKP, CK2 DO 20 K=10.200.1 PEK CK1=0.01*P C=12.0**2.0*36000.0**2.5*(1.0+2.0*CK1**2.0*CK2)**2.0*CK1**4.0*CK2/ I(CKP**0.5*3.14**2.0*3000000.0**1.5*(1.0+6.0*CK1**2.0*CK2)**2.0) 2/0.0 WRITE(6,100)S,CK1,CK2,C 20 35 10 101 99 STOP END

KSZNY KOMPOTER CENTER	MAIN	DA	TE = 72229	20/15/59 107
	IRAL DESIGN H-SE		ASSIVE CONSTR	AINI
100 FORNAT(5F15.5) 101 READ(5,100,END: 10 20 K=10,200	=991S,CKP,CKZ			
D=K: CK1=G.01*D A=3.14*CK1**2.0	0*6K2**0.5*30000	000.0**0.7	5/(1.0+2.0*CK	1**2.0*6<2)/
1CK1**2.0*CK2)/	1.0*CK1**3.0*CK2 (6.0**0.75*CKP**			5/(1.0+6.0*
PL2=X1**4.0	0*4*C)**0.5-81/2	.0/A		
20 WRITE(6,100)S,0 GO TO 101 92 STCP	SK1,X1,PL2			
END				

19/16/57

UFTIMUM STRUCTURAL DESIGN H-SELLTUN SA & KI RELATION K1=CK1 SA=DESIGN STRESS 100 FORMAT (5F15.5) TOI READ (5, 100, END=99) S, CKP, CK2 DO 20 K=5,128,1 P=K UK 1= 0. 01 * P SA=(12.0**0.5*CK1**4.0*CK2*1.0*S*3.14*3000000.0**0.5*(1.0+2.0*CK1 1**2.0*CK2)**0.5/((1.0+6.0*CK1**2.0*CK2)**1.5-02.0*CK1**4.0*CK2*(1. 20+6.0*CK1**7.0*CK2)**0.5))**2.0 WRITE(6,100)S.CK1,CK2,SA 20 GO TO 101 STOP 99 END

IEVEL 20 MAIN DATE = 72234 19/19/15 UPTIMUM STRUCTURAL DESIGN H-SECTION RELATION BETWEEN P/L**2 & SA & K1 100 FORMAT (5F15.5) READ (5, 100, END=99)5, CKP, CK2 IUI 00 20 K=5,128,1 P=K CKI=J.OI*P SA=(12.0**0.5*CK1**4.0*CK2*1.0*S*3.14*3000000.0**0.5*(1.0+2.0*CK1 1**2.0*CK2)**U.5/((1.0+6.0*CK1**2.0*CK2)**1.5-02.0*CK1**4.0*CK2*(1. 20+5.0°CK1**2.0°CK2)**0.51)**2.0 C=12.0**1.5*SA**3.0*(1.0+2.0*CK1**2.0*CK2)**2.0/CKP**0.5/(3.14**2. 10*3000000.0**1.5*(1.0+6.0*CK1**2.0*CK2)*12.0**0.5*SA**0.5+6.0*S* 23.14**3.0*30000000.0**2.0*(1.0+0.0*CK1**2.0*CK2)**0.5*(1.0+2.0*CK1 3**2.0*CK21**0.51 WPITE(6,100)S,CK1,SA.C 20 60 10 101 99 STOP END)

C CPTIMUM STRUCTURAL DESIGN H-SECTION

MELATION BETWEEN AREA & KI WHEN SA SY

100 FORMAT(5F15.5)

101 READ(5,100,ENL=94)S,CKP,CK2,CK1,SA

AL2=12.0*SA**1.5*(1.0+2.0*CK1**2.0*CK2)**2.0/(CKP**0.5*3.14**2.0*3

10000000.0**1.5)/(1.0+6.0*CK1**2.0*CK2)*10000.0

WRITE(6,100)S,CK1,SA,AL2

GO TC 101

99 SIEP

EMD

CPTIMUM STRUCTURAL DESIGN H-SECTION C RELATION BETHEEN PLZ & KI WHEN FC? IS PASSIVE CONSTRAINT RELATION BETWEEN AREA EPLZ WHEN SA = SY C 100 FORMAT(5F15.5) 101 REAU(5, 100, ENU=99)8, CKP, CK2 00 20 K=10,200,2 D=F CK1=0.01*D A=3.14*CK1**Z.0*CK2**0.5*30000000.0**0.75/(1.0+2.0*CK1**Z.0*CK2)/ 14.0**0.5 B=6.0*5*3.14**1.5*CK1**3.0*CK2**0.75*30000000.0**0.875/(1.0+6.0* 1CK1**2.0*CK2)/(6.0**0.75*LKP**0.125)*36000.0**0.125 C=36000.04#1.25/0KP##0.25 X1=(()**2.0+4.0*A*C)**0.5-0)/2.0/A PL2=X1**4.0 AL2=(6.0*PL2)**0.5*(36000.0/CKP)**0.25*(1.0+2.0*CK1**2.0*CK2)/(3.1 14*3UC00000.0**C.75*CK1**Z.6*CK2**0.5)*10000.0 WRITE(6,100)5,CK1,X1,PL2, MLZ 20

GC TC 101

STOP

EL 20 MAIN DATE = 7223419/21/35 DETIMUM STRUCTURAL DESIGN RECTANGULAR TUBE SECTION C & K1 PELATION FOR PSI-Y=1 P/L**2=C K1=CK1 RELATION BETWEEN P/L ## 2 & KI IN EQUATION (3.14) FURMAT (5-15.5) READ (5, 100, END=9915, CKP, CK2 00 20 K=10,200.1 PEK CK != 0.01*P C=12.0**1.5*36000.0**3.0*(1.0+CK1**2.0*CK2)**2.0/CKP**0.5/(3.0*S*3 T.14**3.0*30000000.0**2.0*(1.0+3.0*CK1**2.0*(K2)**0.5*(1.0+CK1**2.0 2*CK2)**.5+3.14**2.0*30000000.0**1.5*(1.0+3.0*CK1**2.0*CK2)*36000.0 3**(0.5*3.0**0.5) WEITE (6, 103) S, CKI, CKZ, C GO TO 101 STOP FND

C

RELATION RETALLED C. E CKI FOR PSIEY=1 C=P/L**Z CKI=KI RELATION BET, EEN P/L**2 & KI IN COMMITTEN (3.17) C

FORMAT(5015.51 100

READ (5.100, EMD=99)5, CKP, CK2 101

De 20 8=10.200.1 .

D=K

CK1=0.01*P

C=24.0*36000.0**2.9*(CK1**4.0*CK2+3.0*CK1**2.0)*(1.0+CK1**2.0*CK2) 1 ** 7 . U/(CKP ** C.5*3.14 ** 2.0*3.000000.0**1.5*(1.0+3.0*Ck1**2.0*Ck2) **

FRITE(6,100)S,CK1,CK2,C 20 90-10-101

99 STOP END ...

LENGE LCOMPOSTER	CENTER	MAIN		DATE = 72229	20/16/20114
REL/	ATION BETHELD			TUBE SECTION S PASSIVE CUNSTR	AINI
101 REAL	MAT(5F15.5) 0(5.100.ENL=9 20 K=10.200.2		K2		
D=K CK1=	=0.01*D		0.0550 75516	K1**4.0*CK2+3.0*	CK1**7 (1)**0:
15/(2 8=3	2.0*6.0**U.5* .14**1.5*3.U*	36000.0** 5*3000000	0.25)/(1.0+Ck	K1**2.0*CK2) CK1**4.U*CK2+3.U	*CK1**2.0)**
C=36 X1=(5600.0/CKP**0 ((2**2.0+4.0*	.125		3.0*CK1**2.0*CK2)
	=X1**4.0 TE(6.100)S,CK	1 V1 012			
G0 1	10 101	TINTIFLE			
99 STOP END					
CMO					
- 50 a C d					

EVFL 20 MATN 19/58/20 DATE = 72234 DPTIMUM STRUCTURAL DESIGN RECTANGULAR TUBE SECTION RELATION BETWEEN P/L ##2 & SA & KI 100 FORMAT (5F15.5) READ(5,100,END=99)S,CKP,CKZ 101 DO 20 K=5, 49,1 D=K CK1=0.01 #F 5A=3.0*S**2.0*3.14**2.0*30000000.0*(CK1**4.0*CK2+3.0*CK1**2.0)**2. 10*(1.0+CK1**2.0*CK2)/(1.0+3.0*CK1**2.0*CK2)/(1.0+3.0*CK1**2.0*CK2-2CK 1**+.U*CK2-3.U*CK1**2.01**2.0 C=24.0*SA**3.0*(1.0+CK1**2.0*CK2)**2.0/CKP**0.5/(3.0**0.5*S*3.14** 13.0*30000000.0**2.0*(1.0+3.0*CK)**2.0*CK2)**0.5*(1.0+CK1**2.0*CK2) 2**U.5+3.14**2.U*30U0UUUU.U**1.5*(1.0+3.U*CK1**2.U*CK2)*SA**U.5) 20 WRITE(6,100)S,CK1,SA,C GO TO 101 STOP ENU

C PTIMUM STRUCTURAL DESIGN RECTANGULAR TUBE SECTION

C RELATION BETWEEN AREA & KI WHEN S' - SY

100 FORMAT(5F15.5)

101 REAC(5,100, END=9915, CKP, CK2, CK1, SA AL2=24.0*(SA/30000000.0)**1.5*(1.0+CK1**2.0*CK2)**2.0/(CKP**0.5*3. 114 # # 2 . 0) / (1 . C + 3 . C # C K 1 # # 2 . U # C K 2) # 10 0 C G . 0 -WRITE (6,100) S.CK1.SA.AL2

30 10 101

99 STOP END

G LEVEL 20

EVEL 20

100

101

20

99

GO TO 101

STOP

OPTIMUM STRUCTURAL DESIGN RECTANGULAR TUBE SECTION RELATION BETWEEN PL2 & K1 WHEN FC3 IS PASSIVE CONSTRAINT RELATION BETWEEN AREA EPL2 WHEN SA = SY FORMAT (5F15.5) READ (5,100, END=99) S.CKP, CK2 DO 20 K=10.200.2 D=K CK 1=0.005*D A=3.14*CKP**0.125*30000000.0**0.75*(CK1**4.0*CK2+3.0*CK1**2.0)**0. 15/(2.0*6.0**0.5*36000.0**0.25)/(1.0+CK1**2.0*CK2) B=3.14**1.5*3.0*S*3.0000000.0**0.375*(CK1**4.0*CK2+3.0*CK1**2.0)** 10.75/(6.0**C.75*36000.0**0.125)/(1.0+3.0*CK1**2.0*CK2) C=36000.0/CKP**0.125 X1=((B**2.0+4.0*A*C)**0.5-3)/2.0/A PL2=X1**4.0 AL2=(6.0*PL2)**0.5*(36000.0/CKP)**0.25*(1.0+CK1**2.0*CK2)/3.14/300 100000.0**0.75/(CK1**4.0*CK2+3.0*CK1**2.0)**0.5*2.0*10000.0 WRITE(6,100)S.CK1.X1.PL2.AL2

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